

Viscoelastic flows of Maxwell fluids with conservation laws

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Abstract

Maxwell introduced a 1D *causal* relaxation model for viscoelastic fluid flows, where information propagates at *finite* speed. Most viscoelastic models for multi-dimensional flows (Oldroyd-B etc.) add diffusion and lack the *local* character of Maxwell model ! Here, a *symmetric-hyperbolic system of conservation laws* defines multi-D viscoelastic compressible flows as extensions of polyconvex elastodynamics. In the shallow-water regime, the system reduces to a useful viscoelastic extension of Saint-Venant 2D model.

Elastic and viscous motions in continuum mechanics

- Bodies \mathcal{B} are Riemannian manifolds with metric $G_{\alpha\beta} \in S^{++}(\mathbb{R}^{d \times d})$, $d = 3$ in coordinates $\{\mathbf{a}^\alpha\}$; flows are configurations $\phi_t(\mathcal{B})$, $t \in \mathbb{R}$ into the Euclidean ambient space with a given force field \mathbf{f} , $\mathbf{f}^i e_i$ in coordinates $\{\mathbf{x}^i\}$

- Galilean-invariant balance of total energy $E \geq 0$ holds given heat supply \mathbf{R}

$$\partial_t(E \circ \phi_t) = \text{div}_a(S^{i\alpha} \partial_t \phi_t^i) + \partial_t \phi_t^i (f^i \circ \phi_t) + \mathbf{R} \quad (1)$$

- Momentum balance holds with mass-density $\hat{\rho}(\mathbf{a}) \geq 0$

$$\hat{\rho}(\partial_t^2 \phi_t) = \text{div}_a \mathbf{S} + \hat{\rho}(\mathbf{f} \circ \phi_t) \quad (2)$$

given $\mathbf{r} \circ \phi_t = \mathbf{R}/\hat{\rho}$ and internal energy $e \circ \phi_t := \frac{1}{\hat{\rho}} \mathbf{E} \circ \phi_t - \frac{1}{2} |\partial_t \phi_t|^2$

$$\hat{\rho}(\partial_t e \circ \phi_t) - S^{i\alpha} \partial_t^2 \phi_t^i = \hat{\rho}(\mathbf{r} \circ \phi_t) \quad (3)$$

where Piola-Kirchoff stress \mathbf{S} satisfies $S^{i\alpha} \partial_\alpha \phi_t^j = S^{j\alpha} \partial_\alpha \phi_t^i$.

- Smooth motions with $\mathbf{F}_\alpha^i := \partial_\alpha \phi_t^i \circ \phi_t^{-1}$, $\mathbf{u}^i := \partial_t \phi_t^i \circ \phi_t^{-1}$ are defined by, for e.g. *Neo-Hookean elastic* (solid) bodies $e(\mathbf{F}_\alpha^k \mathbf{F}_\alpha^k) := \frac{\mu}{2} (\mathbf{F}_\alpha^k \mathbf{F}_\alpha^k - d)$,

$$\partial_t(\hat{\rho} \mathbf{u}^i \circ \phi_t) - \partial_\alpha S^{i\alpha} = \hat{\rho} f^i \quad (4)$$

$$\partial_t(\mathbf{F}_\alpha^i \circ \phi_t) - \partial_\alpha(\mathbf{u}^i \circ \phi_t) = 0$$

$$\partial_t(|\mathbf{F}_\alpha^i| \circ \phi_t) - \partial_\alpha(C_j^{\alpha i} \circ \phi_t \mathbf{u}^j \circ \phi_t) = 0$$

$$\partial_t(C_i^\alpha \circ \phi_t) + \sigma_{ijk} \sigma_{\alpha\beta\gamma} \partial_\beta(\mathbf{F}_\gamma^j \circ \phi_t \mathbf{u}^k \circ \phi_t) = 0$$

with $S^{i\alpha} = \hat{\rho} \partial_{F_\alpha^i} e$, $C_i^\alpha = \sigma_{ijk} \sigma_{\alpha\beta\gamma} \mathbf{F}_\beta^j \mathbf{F}_\gamma^k$ and Levi-Civita symbol σ_{ijk} , or

$$\partial_t(\rho \mathbf{u}^i) + \partial_j(\rho \mathbf{u}^j \mathbf{u}^i - \sigma^{ij}) = \rho f^i \quad (5)$$

$$\partial_t(\rho \mathbf{F}_\alpha^i) + \partial_j(\rho \mathbf{u}^j \mathbf{F}_\alpha^i - \rho \mathbf{F}_\alpha^j \mathbf{u}^i) = 0$$

$$\partial_t \rho + \partial_j(\rho \mathbf{u}^j) = 0$$

$$\partial_t(\rho C_i^\alpha) + \partial_j(\rho \mathbf{u}^j C_i^\alpha) + \sigma_{ijk} \sigma_{\alpha\beta\gamma} \partial_l(|\mathbf{F}_\alpha^i|^{-1} \mathbf{F}_\beta^l \mathbf{F}_\gamma^j \mathbf{u}^k) = 0$$

with Cauchy stress $\sigma^{ij} := |\mathbf{F}_\alpha^i|^{-1} \mathbf{F}_\alpha^j S^{i\alpha} \circ \phi_t^{-1}$ and $\rho := |\mathbf{F}_\alpha^i|^{-1} \hat{\rho}$.

$$\text{Recall Piola's identities: } \partial_j(|\mathbf{F}_\alpha^i|^{-1} \mathbf{F}_\alpha^j) = 0 \quad \forall i = 1 \dots d. \quad (6)$$

- Polytropic* fluids $e(\rho) := \frac{C_0}{\gamma-1} \rho^{\gamma-1}$, $\sigma^{ij} = (-C_0 \rho^\gamma) \delta^{ij} + \tau^{ij}$ can be viscous

$$\tau^{ij} = 2\dot{\mu} D(\mathbf{u})^{ij} + \ell D(\mathbf{u})^{kk} \delta_{ij} \quad (7)$$

insofar as τ^{ij} is objective and $\partial_t \eta + (\mathbf{u}^j \partial_j) \eta := \tau^{ij} D(\mathbf{u})^{ij} / \theta \geq 0$

- Instead of entropy η one often uses temperature $\theta = -\partial_\eta e$ and $\psi = e - \theta \eta$

$$\hat{\rho}((\eta \circ \phi_t) \partial_t(\theta \circ \phi_t) + \partial_t(\psi \circ \phi_t)) - S^{i\alpha} \partial_\alpha(\mathbf{u}^i \circ \phi_t) = -\hat{\rho} D \circ \phi_t \quad (8)$$

with $S^{i\alpha} = \hat{\rho} \partial_{F_\alpha^i} \psi$, $\eta = -\partial_\theta \psi$ and a dissipation $D \geq 0$

Viscoelastic flows by Maxwell fluids

- Assume $\psi = \frac{C_0(\theta)}{\gamma-1} \rho^{\gamma-1} + \mathcal{F}(c, \theta)$ with $c \approx \mathbb{E}(\mathbf{R} \otimes \mathbf{R})$ given by

$$d\mathbf{R}^i = \left(-(\mathbf{u}^j \partial_j) \mathbf{R}^i + (\partial_j \mathbf{u}^i) \mathbf{R}^j - \frac{2K}{\xi} \mathbf{F}^i(\mathbf{R}) \right) dt + \sqrt{\frac{4k_B \theta}{\xi}} dW^i(t) \quad (9)$$

where ξ denotes friction, and $K(\theta)$ a spring factor for $\mathbf{F}^i(\mathbf{R}) = \mathcal{H}' \mathbf{R}^i$

- If \mathcal{H}' is constant, then \mathbf{R} is Gaussian and it exactly holds

$$c^{ij} = -\frac{4K\mathcal{H}'}{\xi} c^{ij} + \frac{4k_B \theta}{\xi} \delta^{ij} \quad (10)$$

with $\dot{c}^{ij} = \partial_t \tau^{ij} + \mathbf{u}^k \partial_k \tau^{ij} - \partial_k \mathbf{u}^i \tau^{kj} - \tau^{ik} \partial_k \mathbf{u}^j$. A dissipative choice is

$$\mathcal{F} = K\mathcal{H}'(\text{tr}(c)) - k_B \theta \log |c|, \quad \tau^{ij} = 2\rho(K\mathcal{H}' c^{ij} - k_B \theta \delta^{ij}). \quad (11)$$

It produces the *Upper-Convected Maxwell* (UCM) rheological equation

$$\lambda \dot{\tau} + \text{div} \mathbf{u} \lambda \tau + \tau = 2\dot{\mu} D(\mathbf{u}) \quad (12)$$

with $\lambda = 4K\mathcal{H}'/\zeta$, $\dot{\mu}/\lambda = \mu = 2\rho k_B \theta$, & well-defined motions... if *ID* !

- Now, in smooth motions, $A^{\alpha\beta} = [F^{-1}]_i^\alpha c^{ij} [F^{-1}]_j^\beta$ satisfies

$$\partial_t(A^{\alpha\beta} \circ \phi_t) = \frac{4k_B \theta}{\xi} ([F^{-1}]_i^\alpha \circ \phi_t [F^{-1}]_i^\beta) - \frac{4K\mathcal{H}'}{\xi} (A^{\alpha\beta} \circ \phi_t) \quad (13)$$

- K-BKZ fluids have well-defined motions by an *integro-differential* system using

$$c^{ij} \circ \phi_t = \frac{k_B \theta}{K\mathcal{H}'} \int_{t_0}^t ds \frac{1}{\lambda} e^{-\frac{s-t}{\lambda}} (\mathbf{F}_\alpha^i \circ \phi_t [F^{-1}]_k^\alpha \circ \phi_s) ([F^{-1}]_k^\beta \circ \phi_s \mathbf{F}_\beta^j \circ \phi_t) \quad (14)$$

- Here, we propose the following *system of conservation laws* for UCM fluids:

Isothermal viscoelastic flows of compressible UCM fluids

$$\begin{aligned} \partial_t(\rho \mathbf{u}^i) + \partial_j(\rho \mathbf{u}^j \mathbf{u}^i + (p + 2\rho k_B \theta) \delta^{ij} - 2\rho K\mathcal{H}' F_\alpha^i A^{\alpha\beta} F_\beta^j) &= \rho f^i \\ \partial_t(\rho F_\alpha^i) + \partial_j(\rho \mathbf{u}^j F_\alpha^i - \rho \mathbf{u}^i F_\alpha^j) &= 0 \\ \partial_t \rho + \partial_i(\mathbf{u}^i \rho) &= 0 \end{aligned} \quad (15)$$

$$\partial_t(\rho A^{\alpha\beta}) + \partial_j(\rho \mathbf{u}^j A^{\alpha\beta}) = \frac{4\rho}{\xi} (k_B \theta ([F^{-1}]_i^\alpha [F^{-1}]_i^\beta) - K\mathcal{H}' A^{\alpha\beta})$$

Theorem: well-posed Cauchy problems on small times

The system of conservation laws (15) admits univoque classical solutions $C^1([0, T] \times \mathbb{R}^d)$ in $\mathcal{A}^+ := \{\rho > 0, A = A^T > 0\}$ for small enough $T > 0$.

Proof Cauchy problems are well-posed on small times for systems of conservation laws that are symmetric-hyperbolic, with a *strictly* convex extension (i.e. with an additional conservation law for a “mathematical entropy” strictly convex in conservative variables).

Application to free-surface gravity flows in shallow-water regime

- Hydraulics often considers flows under $(f^x, f^y, f^z) := (0, 0, -g)$ of fluids filling $\mathcal{D}_t := \{z^b(x, y) < z < z^b(x, y) + H(t, x, y)\}$ with $0 \leq H \ll L$ given by

$$\partial_t H + \mathbf{u}^x \partial_x(z^b + H) + \mathbf{u}^y \partial_y(z^b + H) = \mathbf{u}^z \sqrt{1 + |\nabla_H(z^b + H)|^2} \quad (16)$$

$\nabla_H = (\partial_x, \partial_y)$, & with $\nabla_H z^b \ll H/L$, $\tau_\epsilon^{xz}, \tau_\epsilon^{yz} \ll \rho_0 g L$ given $L > 0$, $\rho \equiv \rho_0$.

- The free-surface flows (16)–(5) with small Navier friction k at boundaries and $\mathbf{U}^i := \frac{1}{H} \int_{z^b}^{z^b+H} \mathbf{u}^i = \mathbf{u}^i + O(H/L)^2$, $i = x, y$ are approximately 2D. One uses

$$\partial_t H + \text{div}_H(H\mathbf{U}) = 0 \quad (17)$$

$$\partial_t(H\mathbf{U}) + \text{div}_H(H\mathbf{U} \otimes \mathbf{U} - H\Sigma) = -gH\nabla_H(z^b + H) - kH\mathbf{U} \quad (18)$$

with e.g. $\Sigma := \frac{1}{\rho_0 H} \int_{z^b}^{z^b+H} dz (\tau^{ij} - \tau^{zz}) = \nu (\nabla_H \mathbf{U} + \nabla_H \mathbf{U}^T - 2I \text{div}_H \mathbf{U}) \ll gL$.

- Using (15), Saint-Venant system (17)–(18) can be extended to viscoelastic flows:

$$\Sigma = \mathcal{G}H(\mathbf{F}^H \mathbf{A}^H (\mathbf{F}^H)^T - (A^{cc} H^2) I) \quad H = \hat{H} |\mathbf{F}^H|^{-1}, \hat{H} > 0$$

$$\partial_t(H\mathbf{F}^H) + \text{div}_H(H\mathbf{U} \otimes \mathbf{F}^H - H\mathbf{F}^H \otimes \mathbf{U}) = 0$$

$$\partial_t(H\mathbf{A}^H) + \text{div}_H(H\mathbf{U}\mathbf{A}^H) = H((\mathbf{F}^H)^T \mathbf{F}^H)^{-1} - \mathbf{A}^H / \lambda$$

$$\partial_t(H\mathbf{A}^{cc}) + \text{div}_H(H\mathbf{U}\mathbf{A}^{cc}) = H(H^{-2} - A^{cc}) / \lambda \quad (19)$$

- The system of conservation laws (17)–(18)–(19) is symmetric-hyperbolic in $\mathcal{A}_H^+ := \{\rho > 0, \mathbf{A}^H = (\mathbf{A}^H)^T > 0\}$. Given smooth initial values at $t = 0$, it has univoque classical solutions in $C^1([0, T] \times \mathbb{R}^d)$ for small $T > 0$, equivalently defined in Lagrangian description by $\mathbf{U} \circ \Phi_t^H = \partial_t \Phi_t^H$, $\mathbf{F}^H \circ \Phi_t^H = \nabla_H \Phi_t^H$.

- Viscoelastic shear wave flows like $\Phi_t^H(\mathbf{a}) = \mathbf{a} + \mathbf{X}(t, \mathbf{b}) e_{\mathbf{a}}$, $\mathbf{X}(t \leq 0, \mathbf{b}) = 0$, $\mathbf{X}(t, 0) = \Delta \mathbf{X} \cdot \mathbf{1}_{t>0}$ for $\mathbf{b} > 0$ sol. of (20) can be considered beyond 1D!

$$\begin{aligned} \partial_{tt}^2 \mathbf{X}(t, \mathbf{b}) - \mathcal{G}_\epsilon \partial_{bb}^2 \mathbf{X}(t, \mathbf{b}) \\ = \frac{\mathcal{G}_\epsilon}{\lambda} \int_0^t ds e^{-\frac{t-s}{\lambda}} \partial_{bb}^2 \mathbf{X}(s, \mathbf{b}) \quad t, \mathbf{b} > 0 \end{aligned} \quad (20)$$

i.e., since $\partial_{bb}^2 \mathbf{X}(t, \mathbf{b}) = 0 = \partial_t \mathbf{X}(t, \mathbf{b})$, $t \leq 0$:

$$\omega \hat{\mathbf{X}} = \frac{\mathcal{G}_\epsilon}{\omega + \frac{1}{\lambda}} \partial_{bb}^2 \hat{\mathbf{X}}$$

is solved using $\hat{\mathbf{X}}(\omega, \mathbf{b}) = \int_0^\infty dt e^{-\omega t} \mathbf{X}(t, \mathbf{b})$:

$$\frac{\mathbf{X}}{\Delta \mathbf{X}} = \left(e^{-y} + y \int_y^{\frac{t}{\lambda}} dr \frac{I_1(\sqrt{r^2 - y^2})}{e^r \sqrt{r^2 - y^2}} \right) \mathbf{1}_{t > \frac{b}{\sqrt{\mathcal{G}_\epsilon}}$$

and numerically computed in Fig. 1

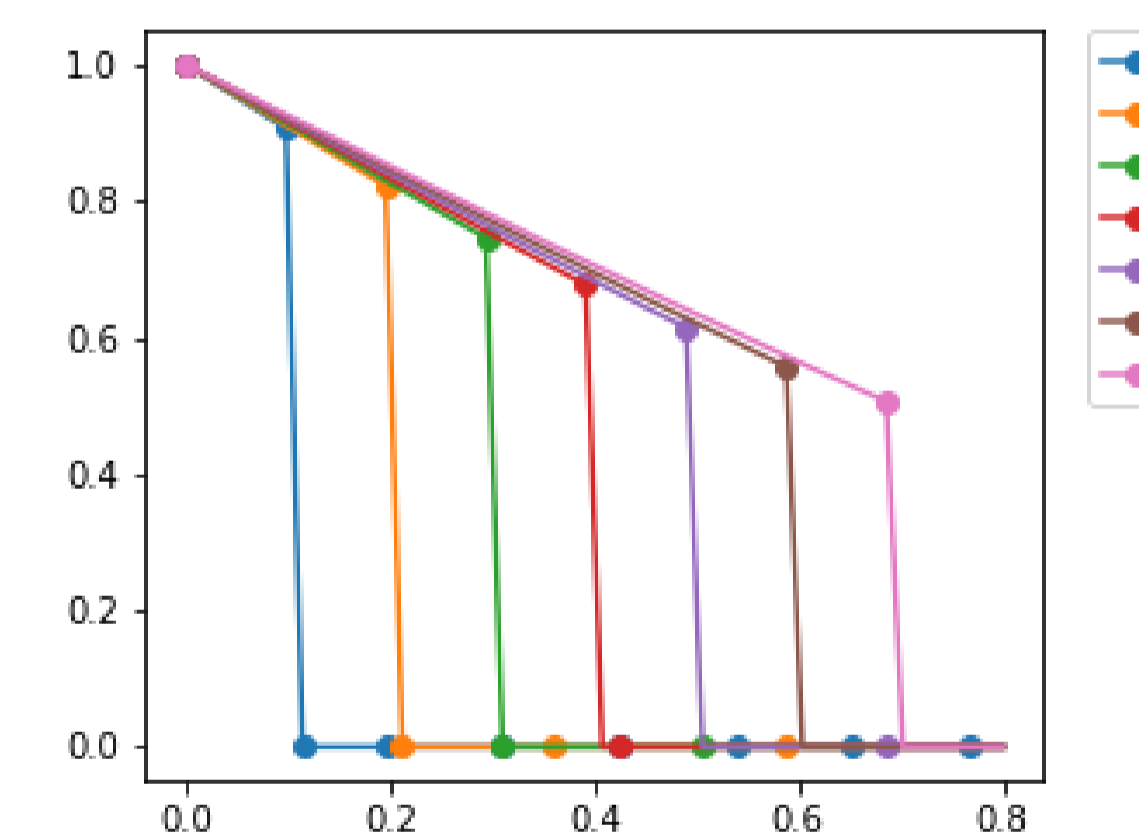


Figure 1: 1D shear wave $X/\Delta X$ function of $y = b/\lambda\sqrt{\mathcal{G}_\epsilon}$ at $t/\lambda \in \{.1, .2 \dots .7\}$.

Conclusion

- Multi-dimensional* (smooth) viscoelastic flows of Maxwell fluids are now well-defined by conservation laws, (15) or (17)–(18)–(19).
- Key to the new viscoelastic systems are *material variables* added into polyconvex elastodynamics (for hyperelastic continuum), here to model *viscous* inelasticities.
- The framework reaches Navier-Stokes after relaxation, and covers many rheologies.

All preprints (and references, therein) are on <http://hal.archives-ouvertes.fr/>.