# Corrigendum and addendum to: "Sided and symmetrized Bregman centroids" IEEE Transactions on Information Theory 55.6 (2009): 2882-2904.

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#### Abstract

We correct and extend the results presented in [12].

### 1 Dissimilarities, dual centroids, and dual information radii

Let D(P:Q) denote the *dissimilarity* between two points P and Q of a space  $\mathbb{G}$  such that  $D(P:Q) \ge 0$  with equality if and only if P = Q. By analogy with the notion of Fréchet barycenters in metric spaces [7], we define the *D*-barycenters or *D*-centroid  $C_D(\mathcal{P})$  of a weighted point set  $\mathcal{P} = \{P_1, \ldots, P_n\}$  with respect to D as

$$C_D(\mathcal{P}) := \arg\min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D(P_i : X), \tag{1}$$

where  $w_i > 0$  and  $\sum_{i=1}^{n} w_i = 1$  (i.e., w belongs to the (n-1)-dimensional standard simplex  $\Delta_{n-1}$ ). The centroids are special cases of barycenters obtained for the uniform weighting  $w_i = \frac{1}{n}$ . Notice that  $C_D(\mathcal{P})$  is generally a subset of points of  $\mathbb{G}$ , and may not necessarily exist nor be unique. For example, the centroid of two antipodal points on the unit Euclidean sphere is a great circle. In Riemannian geometry, other notions of barycenters have been defined [1]: Karcher local barycenters, exponential barycenters, etc.

Since D may be asymmetric  $D(P:Q) \neq D(Q:P)$  (oriented dissimilarity, hence the delimiter notation ":"), we define the *dual dissimilarity*  $D^*(P:Q) := D(Q:P)$ , and the *dual D-barycenter* or *left-sided D-barycenter*:

$$C_D^*(\mathcal{P}) := \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D(X : P_i),$$
(2)

$$= \arg\min_{X \in \mathbb{G}} \sum_{i=1}^{n} w_i D^*(P_i : X), \tag{3}$$

$$= C_{D^*}(\mathcal{P}). \tag{4}$$

Notice that the dual of the dual dissimilarity is the original (primal) dissimilarity:  $D^{**} = D$  (involutive property of duality).

Let  $C_D(\mathcal{P})$  be the primal *D*-barycenter (*right-sided D-barycenter*) and  $C_D^*(\mathcal{P})$  be the dual *D*-barycenter (left-sided *D*-barycenter). The dual *D*-barycenter with respect to *D* amounts to the (primal) *D*<sup>\*</sup>-barycenter for the dual dissimilarity *D*<sup>\*</sup>. When *D* is the squared Euclidean distance, both primal and dual centroids coincide to the center of mass.

The (primal) information radius [13] is defined by

$$I_D(\mathcal{P}) := \sum_{i=1}^n w_i D(P_i : C), \quad C \in C_D(\mathcal{P}),$$
(5)

while the *dual information radius* is defined by

$$I_D^*(\mathcal{P}) := \sum_{i=1}^n w_i D(C:P_i), \quad C \in C_D^*(\mathcal{P}).$$
(6)

In general, we have  $I_D^*(\mathcal{P}) \neq I_{D^*}(\mathcal{P})$  because the left-sided and right-sided centroids may not coincide. (They coincide by default when the dissimilarity is symmetric.) The information radius for the squared Euclidean distance represents the variance of the point set.

# 2 Bregman centroids and Bregman information

Let  $F(\theta)$  be a strictly convex and differentiable real-valued function for  $\theta \in \Theta$ , where  $\Theta \subset \mathbb{R}^D$  denotes the open parameter space. We define the *Bregman divergence* [6] with respect to generator F as:

$$B_F(\theta:\theta') := F(\theta) - F(\theta') - (\theta - \theta')^\top \nabla F(\theta'), \tag{7}$$

for  $\theta, \theta' \in \Theta$ .

Bregman divergences are canonical smooth dissimilarities of *dually flat space* in information geometry [2, 8]: That is, we can build a canonical Bregman divergence from any dually flat space, and a Bregman divergence yields a dually flat space [3]. In a dually flat space (or *Bregman manifold* [9]), the dissimilarity between two points P and Q is expressed by

$$D_F(P:Q) := B_F(\theta(P):\theta(Q)), \tag{8}$$

where  $\theta(\cdot)$  is a global (affine) coordinate system used to define the potential function  $F(\theta)$ , see [2, 8]. The dual divergence amounts to a dual Bregman divergence  $B_{F^*}$  as follows:

$$D_F^*(P:Q) = D(Q:P) = B_F(\theta(Q):\theta(P)) = B_{F^*}(\eta(P):\eta(Q)) = D_{F^*}(P:Q),$$
(9)

where  $F^*$  is the Legendre-Fenchel convex conjugate [9], and  $\eta(\theta) = \nabla F(\theta)$  the dual affine global coordinate system [2, 8]. We can introduce the Legendre-Fenchel divergence from the dual potential functions F and  $F^*$  as follows:

$$A_F(\theta:\eta') := F(\theta) + F^*(\eta') - \theta^\top \eta' \ge 0$$
(10)

with equality if and only if  $\eta' = \nabla F(\theta)$ , or equivalently  $\theta = \nabla F^*(\eta')$ .

Thus, in a Bregman manifold, we have the dual divergences that can be expressed using the dual coordinate systems either by Bregman divergences or by Legendre-Fenchel divergences as follows:

$$D_F(P:Q) = B_F(\theta(P):\theta(Q)) = A_F(\theta(P):\eta(Q)) =: D_F^*(Q:P),$$
(11)

$$D_F^*(P:Q) = B_{F^*}(\eta(P):\eta(Q)) = A_{F^*}(\eta(P):\theta(Q)) =: D_F(Q:P).$$
(12)

**Theorem 1** Theorem 3.1 and Theorem 3.2 of [12] Let  $\theta_i = \theta(P_i)$  and  $\eta_i = \eta(P_i)$  be the primal and dual coordinates of point  $P_i$  for  $P_i \in \mathcal{P} = \{P_1, \ldots, P_n\}$ . Let  $\bar{\theta} = \sum_{i=1}^n w_i \theta_i$  and  $\bar{\eta} = \sum_{i=1}^n w_i \eta_i$ denote the center of mass in the primal  $\theta$ -coordinate system and dual  $\eta$ -coordinate system, respectively. The right-sided Bregman centroid  $C_{D_F}(\mathcal{P})$  and the left-sided Bregman centroid  $C_{D_F}^{*}(\mathcal{P})$ exist and are both unique, and we have  $\theta(C_{D_F}(\mathcal{P})) = \overline{\theta}$  and  $\eta(C_{D_F}^*(\mathcal{P})) = \overline{\eta}$ .

**Proof:** We have

$$C_{D_F}(\mathcal{P}) = \arg\min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D_F(P_i : X), \tag{13}$$

$$= \arg\min_{X \in \mathbb{G}} \sum_{i=1}^{n} w_i A_F(\theta_i : \eta(X)), \tag{14}$$

$$= \arg\min_{X \in \mathbb{G}} E(X) = (\sum_{i=1}^{n} w_i F(\theta_i)) + F^*(\eta(X)) - \bar{\theta}^\top \eta(X).$$
(15)

A point  $X \in C_{D_F}(\mathcal{P})$  if and only if  $\nabla_{\eta(X)} = 0$ :  $\nabla_{\eta} F^*(\eta(X)) = \theta$ . That is:

$$\eta(X) = (\nabla F^*)^{-1}(\bar{\theta}) = (\nabla F^*)^{-1}(\sum_{i=1}^n w_i \nabla F^*(\eta_i)).$$
(16)

The right-sided centroid is unique since the Hessian  $\nabla^2_{n(X)}E(X)$  is  $\nabla^2 F^*(\eta(X))$ , and  $\nabla^2 F^*$  is positive-definite ( $F^*$  is a strictly convex conjugate). The right-sided centroid is expressed in the  $\theta$ -coordinate system as  $\theta(C_{D_F}(\mathcal{P})) = (\nabla F^*)(\eta(C_{D_F}(\mathcal{P}))) = (\nabla F^*)((\nabla F^*)^{-1}(\bar{\theta})) = \bar{\theta}.$ 

The proof for the left-sided centroid is similar, and we have  $\theta(C_{D_F}^*(\mathcal{P})) = (\nabla F)^{-1}(\bar{\eta}) =$  $(\nabla F)^{-1}(\sum_{i=1}^{n} w_i \nabla F(\theta_i))$  so that  $C_{D_F}^{*}(\mathcal{P})$  expressed in the  $\eta$ -coordinate system is  $\bar{\eta}$ . 

To summarize, we have:

$$\begin{array}{ccc} \theta \text{-coordinate system} & \eta \text{-coordinate system} \\ \hline \text{Right-sided centroid } C_{D_F}(\mathcal{P}) & \bar{\theta} = \sum_{i=1}^n w_i \theta_i \\ \text{Left-sided centroid } C_{D_F}^*(\mathcal{P}) & (\nabla F)^{-1} (\sum_{i=1}^n w_i \nabla F(\theta_i)) \\ \hline \bar{\eta} = \sum_{i=1}^n w_i \eta_i \end{array}$$

In term of Bregman divergences, the right-sided Bregman centroid is the center of mass [4]. The Bregman information radius is called *Bregman information* in [4]. It was shown in [11, 5] that the only symmetrized Brequinant divergences are squared Mahalanobis divergences. Thus the left-sided centroid and right-sided Bregman centroids coincide only for squared Mahalanobis divergences, and the dual Bregman information radii differ in the general case.

Corollary 1 Correct Corollary 3.3 of [12] The information radius  $I_{D_F}(\mathcal{P})$ =  $J_F(\theta_1,\ldots,\theta_n;w_1,\ldots,w_n)$  where  $J_F$  denotes the Jensen diversity index [10]:

$$J_F(\theta_1, \dots, \theta_n; w_1, \dots, w_n) := \sum_{i=1}^n w_i F(\theta_i) - F\left(\sum_{i=1}^n w_i \theta_i\right) \ge 0.$$
(17)

The dual information radius  $I_{D_F}^{*}(\mathcal{P}) = I_{D_F}^{*}(\mathcal{P}) = J_{F^*}(\eta_1, \ldots, \eta_n; w_1, \ldots, w_n)$  differs from the primal information radius except when  $D_F$  is a squared Mahalanobis divergence.

Thus we have:

$$I_{D_F}(\mathcal{P}) = \sum_{i=1}^n w_i F(\theta_i) - F\left(\sum_{i=1}^n w_i \theta_i\right), \qquad (18)$$

$$I_{D_F^*}(\mathcal{P}) = \sum_{i=1}^n w_i F^*(\eta_i) - F^*\left(\sum_{i=1}^n w_i \eta_i\right).$$
(19)

**Example 1** When  $F(\theta) = \frac{1}{2}\theta^{\top}Q\theta$  for a positive-definite matrix  $Q \succ 0$ , we have the convex conjugate  $F^*(\eta) = \frac{1}{2}\eta^{\top}Q^{-1}\eta$  (with  $Q^{-1} \succ 0$ ). We have  $\eta_i = Q^{-1}\theta_i$  and  $\eta_i = Q\theta_i$ . It follows that  $\bar{\theta} = \sum_{i=1}^n w_i\theta_i = Q^{-1}\bar{\eta}$  and  $\bar{\eta} = \sum_{i=1}^n w_i\eta_i = Q\bar{\theta}$ . Thus we check that the information radii coincide when dealing with squared Mahalanobis Bregman divergences:

$$I_{D_F}(\mathcal{P}) = \sum_{i=1}^n w_i \frac{1}{2} \theta_i^\top Q \theta_i - \frac{1}{2} \bar{\theta}^\top Q \bar{\theta}, \qquad (20)$$

$$= \sum_{i=1}^{n} w_i \frac{1}{2} (Q^{-1} \eta_i)^{\top} Q (Q^{-1} \eta_i) - \frac{1}{2} (Q^{-1} \bar{\eta})^{\top} Q (Q^{-1} \bar{\eta}), \qquad (21)$$

$$= \sum_{i=1}^{n} w_i \eta_i^{\top} Q^{-1} \eta_i - \frac{1}{2} \bar{\eta} Q^{-1} \bar{\eta}, \qquad (22)$$

$$= I_{D_F^*}(\mathcal{P}) = I_{D_F^*}(\mathcal{P}).$$
(23)

Let  $Q = LL^{\top}$  be the Cholesky decomposition of a positive-definite matrix  $Q \succ 0$ . It is wellknown that the Mahalanobis distance  $M_Q$  amounts to the Euclidean distance on affinely transformed points:

$$M_Q^2(\theta, \theta') = \Delta \theta^\top Q \Delta \theta, \tag{24}$$

$$= \Delta \theta^{\top} L L^{\top} \Delta \theta, \qquad (25)$$

$$= M_I^2(L^{\top}\theta, L^{\top}\theta') = \|L^{\top}\theta - L^{\top}\theta'\|^2,$$
(26)

where  $\Delta \theta = \theta' - \theta$ .

The squared Mahalanobis distance  $M_Q^2$  does not satisfy the triangle inequality, but the Mahalanobis distance  $M_Q$  is a metric distance:

$$M_Q(\theta, \theta') = \sqrt{(\theta' - \theta)^\top Q(\theta' - \theta)} = \sqrt{\Delta \theta^\top Q \Delta \theta}.$$

Conversely, we can transform the Euclidean distance as an equivalent Mahalanobis distance on affinely transformed points:

$$M_Q((L^{\top})^{-1}\theta, (L^{\top})^{-1}\theta') = M_I(\theta, \theta') = \|\theta - \theta'\|.$$

Thus the Euclidean distance can be rewritten as the following equivalent Mahalanobis distances:

$$M_{Q_2}((L_2^{\top})^{-1}\theta, (L_2^{\top})^{-1}\theta') = M_{Q_1}((L_1^{\top})^{-1}\theta, (L_1^{\top})^{-1}\theta') = \|\theta - \theta'\| = M_I(\theta, \theta')$$

It follows that we can transform one Mahalanobis distance  $M_{Q_2}$  into another Mahalanobis distance  $M_{Q_1}$  by a linear transformation:

$$M_{Q_2}(\theta, \theta') = M_{Q_1}((L_1^{\top})^{-1}L_2^{\top}\theta, (L_1^{\top})^{-1}L_2^{\top}\theta').$$

Observe that when  $Q_1 = I$ , we have  $L_1 = I$ , and we recover  $M_{Q_2}(\theta, \theta') = M_I(L_2^{\top}\theta, L_2^{\top}\theta') = \|L_2^{\top}\theta - L_2^{\top}\theta'\|$ , as expected.

For any lower triangular matrix, we have  $(L^{-1})^{\top} = (L^{\top})^{-1}$ .

Let  $L_{12} = L_2 \left( \left( L_1^{\top} \right)^{-1} \right)^{\top}$ . Notice that  $L_{12} = L_2 L_1^{-1}$ . Therefore we have  $M_{Q_2}(\theta, \theta') = M_{Q_1}(L_{12}^{\top}\theta, L_{12}^{\top}\theta')$ .

Another short proof consists in writing for symmetric positive-definite (SPD) matrix  $Q = L^{\top}L \succ 0$  that

$$M_Q(\theta_1, \theta_2) = M_I(L^{\top}\theta_1, L^{\top}\theta_2) \Leftrightarrow M_I(\theta_1, \theta_2) = M_Q((L^{\top})^{-1}\theta_1, ((L^{\top})^{-1}\theta_2).$$

Then we have for two SPD matrices  $Q_1 = L_1^{\top} L_1 \succ 0$  and  $Q_2 = L_2^{\top} L_2 \succ 0$ :

$$M_{Q_1}(\theta_1, \theta_2) = M_I(L_1^{\top} \theta_1, L_1^{\top} \theta_2) = M_{Q_2}((L_2^{\top})^{-1} L_1^{\top} \theta_1, (L_2^{\top})^{-1} L_1^{\top} \theta_2).$$

Thus we have

$$M_{Q_1}(\theta_1, \theta_2) = M_{Q_2}((L_2^{\top})^{-1}L_1^{\top}\theta_1, (L_2^{\top})^{-1}L_1^{\top}\theta_2).$$

### 3 The symmetrized Bregman centroids

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