

Bregman divergences, dual information geometry, and generalized comparative convexity

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Outline

- Bregman divergences
- Dual information geometry & Bregman manifolds
- Generalized convexity and designing divergences from convexity gaps

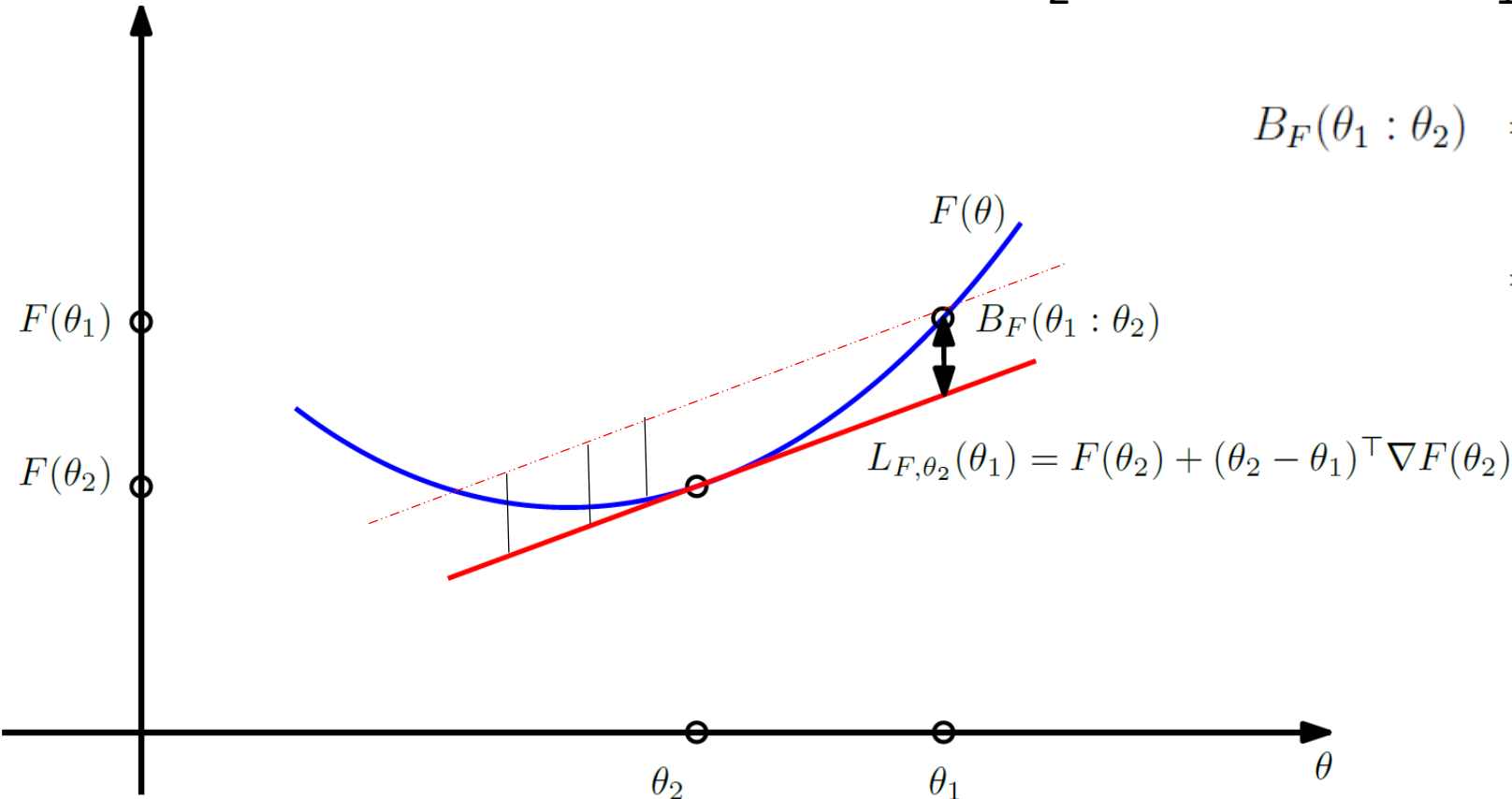
Part I.

Bregman divergences:

- Legendre-Fenchel transformation (dual parameterization)
- Fenchel-Young divergences (mixed parameterization)
- Statistical divergences, statistical models & Bregman divergences

Bregman divergences

- $F(\theta)$: strictly convex and differentiable convex function on an open convex domain Θ
- Design the **Bregman divergence** as the vertical gap between $F(\theta_1)$ and the linear approximation of $F(\theta)$ at θ_2 evaluated at θ_1 :



$$\begin{aligned} B_F(\theta_1 : \theta_2) &= F(\theta_1) - \underbrace{(F(\theta_2) + (\theta_1 - \theta_2)^\top \nabla F(\theta_2))}_{L_{F, \theta_2}(\theta_1)} \\ &= F(\theta_1) - F(\theta_2) - (\theta_1 - \theta_2)^\top \nabla F(\theta_2) \end{aligned}$$

Bregman divergences: Some properties

- **Positive-definite:**

- $B_F(\theta_1 : \theta_2) > 0$ when $\theta_1 \neq \theta_2$
- $B_F(\theta_1 : \theta_2) = 0$ if and only if $\theta_1 = \theta_2$

- **Symmetric** only for **generalized squared Euclidean/Mahalanobis distance**, **asymmetric** otherwise [N+ 2007]

$$Q \succ 0 \quad D_Q^2(\theta_1, \theta_2) = B_{F_Q}(\theta_1, \theta_2) = (\theta_2 - \theta_1)^\top Q (\theta_2 - \theta_1), \quad F_Q(x) = x^\top Q x$$

$$D_E(\theta_1, \theta_2)^2 = \|\theta_1 - \theta_2\|_2^2 = D_I^2(\theta_1, \theta_2)$$

$$M_\Sigma^2[\mathcal{N}(\mu_1, \Sigma), \mathcal{N}(\mu_2, \Sigma)] = D_{\Sigma^{-1}}^2(\mu_1, \mu_2) = \Delta\mu^\top \Sigma^{-1} \Delta\mu$$

- **Does not satisfy the triangle inequality** of metric distances
- **Smooth/differentiable** w.r.t. parameters \Rightarrow **divergences** (contrast functions)

Bregman divergences: 1st order Taylor remainder

- Bregman divergence (BD) can be interpreted as the **mean-value remainder** of a **first-order Taylor expansion** of $F(\theta)$ at θ_2 :

$$F(\theta_1) = \underbrace{F(\theta_2) + (\theta_1 - \theta_2)^\top \nabla F(\theta_2)}_{\text{first-order Taylor expansion}} + \underbrace{R_F(\theta_1 : \theta_2)}_{\text{Taylor remainder}}$$

$$\begin{aligned} R_F(\theta_1 : \theta_2) &= \frac{1}{2}(\theta_2 - \theta_1)^\top \nabla^2 F(\xi)(\theta_2 - \theta_1), \quad \xi \in [\theta_1, \theta_2] \\ &= F(\theta_1) - F(\theta_2) - (\theta_1 - \theta_2)^\top \nabla F(\theta_2) =: B_F(\theta_1 : \theta_2) \end{aligned}$$

- Since F is strictly convex, the Hessian is positive-definite:

$$\nabla^2 F(\theta) \succ 0 \Leftrightarrow \forall x \neq 0, x^\top \nabla^2 F(\theta)x > 0$$

- and this proves that BDs are positive-definite:

$$R_F(\theta_1 : \theta_2) = \frac{1}{2}(\theta_2 - \theta_1)^\top \nabla^2 F(\xi)(\theta_2 - \theta_1) \geq 0$$

Scalar and separable Bregman divergences

- D-variate Bregman divergence w.r.t. parameter $\theta = (\theta^1, \dots, \theta^D)$
- **Separable**: Bregman generator is **sum of univariate/scalar Bregman generators**:

$$F(\theta) := \sum_{i=1}^D F_i(\theta^i)$$

$$B_F(\theta_1 : \theta_2) = \sum_{i=1}^D B_{F_i}(\theta_1^i : \theta_2^i)$$

- For example, generalized square Euclidean distance with diagonal matrix Q

$$Q = \text{diag}(q_1, \dots, q_d)$$

$$B_{F_Q}(\theta_1, \theta_2) = \sum_{i=1}^D q_i (\theta_2^i - \theta_1^i)^2 = \sum_{i=1}^D B_{F_{q_i}}(\theta_1^i : \theta_2^i)$$

$$F_{q_i}(x) = q_i x^2$$

Extended Kullback-Leibler divergence

- **Extended Kullback-Leibler divergence** (eKL) is a D-dimensional separable Bregman divergence induced by the **Shannon negentropy** Bregman generator:

$$\mathcal{D}_{\text{eKL}}[p_{\theta_1}^+ : p_{\theta_2}^+] := \sum_{i=1}^D \theta_1^i \log \frac{\theta_1^i}{\theta_2^i} + \theta_2^i - \theta_1^i =: B_{F_{\text{eKL}}}(\theta_1 : \theta_2)$$

$$F_{\text{eKL}}(\theta) := \sum_{i=1}^D \theta^i \log \theta^i - \theta^i$$

- p^+ means a **positive measure** (not necessarily normalized to a probability)

- When p^+ is normalized:

$$\mathcal{D}_{\text{eKL}}[p_{\lambda_1} : p_{\lambda_2}] := \sum_{i=1}^D \theta_1^i \log \frac{\theta_1^i}{\theta_2^i}$$

- eKL divergence also called **extended relative entropy** in information theory

Discrete Kullback-Leibler divergence: A non-separable Bregman divergence

- The KLD between two **categorical distributions** a.k.a. *multinoulli* amounts to a **non-separable Bregman divergence** on the **natural parameters** of the multinoulli distributions interpreted as an **exponential family**.

$$p_\lambda = (p_\lambda^1, \dots, p_\lambda^d) \in \Delta_{d-1}^\circ, \quad \sum_{i=1}^d p_\lambda^i = 1$$

$$\mathcal{D}_{\text{KL}}[p_{\lambda_1} : p_{\lambda_2}] := \sum_{i=1}^D \lambda_1^i \log \frac{\lambda_1^i}{\lambda_2^i} =: B_{F_{\text{KL}}}(\theta_1 : \theta_2) \quad \theta^i = \log \frac{\lambda^i}{\lambda^D}, i \in \{1, \dots, D = d - 1\}$$

$$F_{\text{KL}}(\theta) = \log\left(1 + \sum_{i=1}^D \exp(\theta_i)\right) =: \underline{\text{LogSumExp}_+(\theta_1, \dots, \theta_D)}$$

LogSumExp is only convex but LogSumExp_+ is strictly convex [NH 2019]

Legendre-Fenchel transformation

- Consider a Bregman generator of **Legendre-type** (proper, lower semi-continuous). Then its **convex conjugate** obtained from the **Legendre-Fenchel transformation** is a Bregman generator of Legendre type.

$$\begin{aligned} F^*(\eta) &= \sup_{\theta \in \Theta} \{\theta^\top \eta - F(\theta)\} \\ &= - \inf_{\theta \in \Theta} \{F(\theta) - \theta^\top \eta\} \end{aligned}$$

Concave programming:

$$F^*(\eta) = \sup_{\theta \in \Theta} \{\theta^\top \eta - F(\theta)\} = \sup_{\theta \in \Theta} \{E(\theta)\}$$

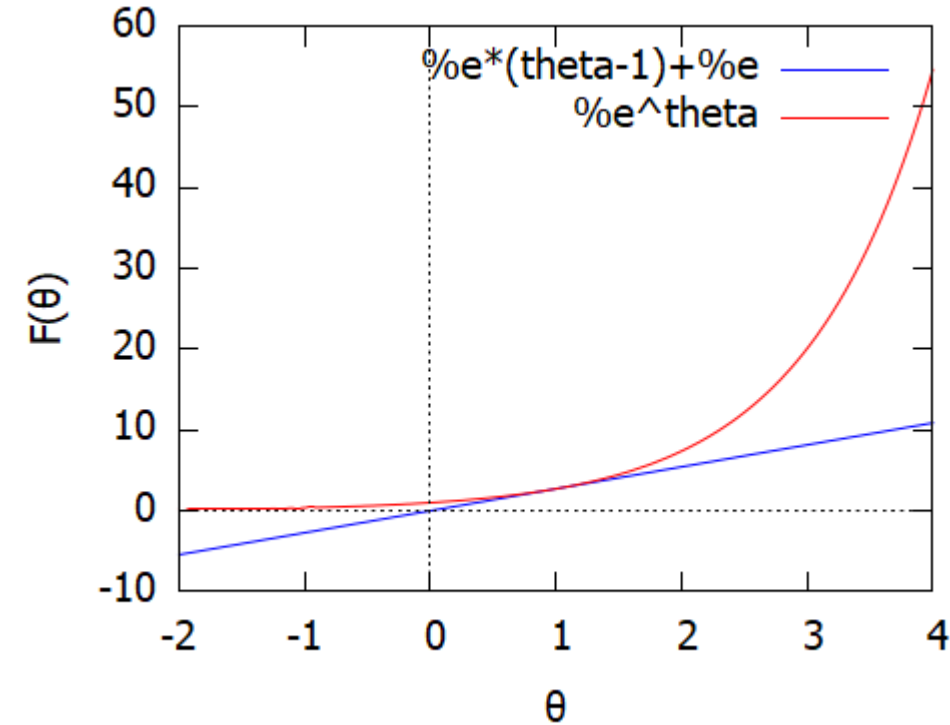
$$\nabla E(\theta) = \eta - \nabla F(\theta) = 0 \Rightarrow \eta = \nabla F(\theta)$$

- Legendre-Fenchel transformation applies to any multivariate function
- Analogy of the Halfspace/Vertex representation of the **epigraph** of F
- Fenchel-Moreau's **biconjugation theorem** for F of Legendre-type: $F = (F^*)^*$

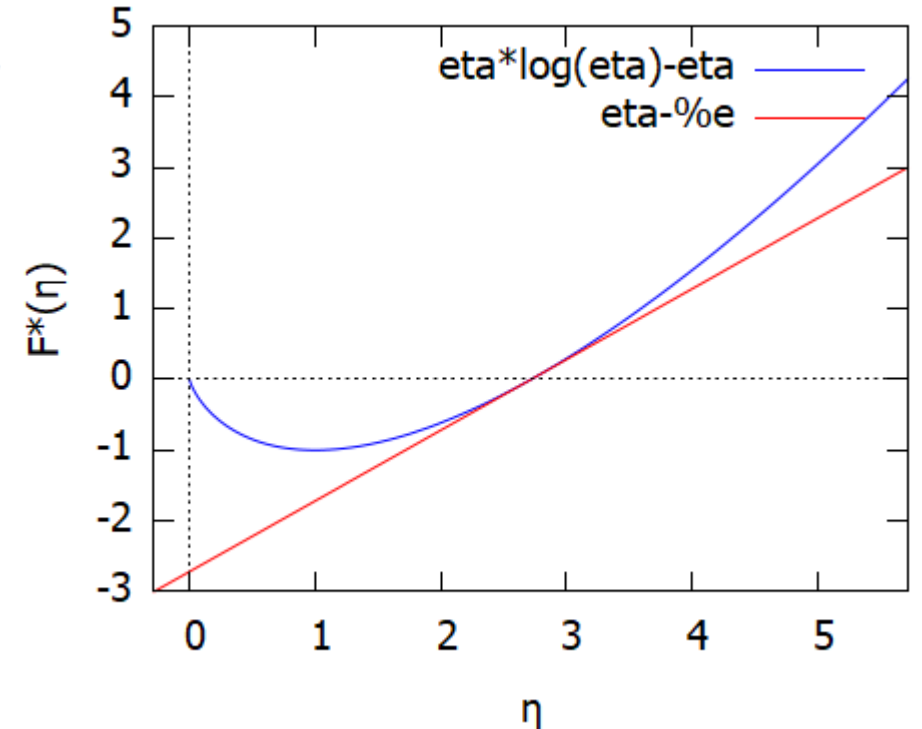
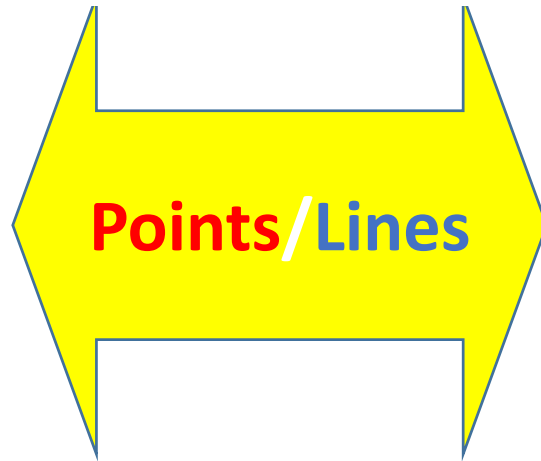
[Touchette 2005] Legendre-Fenchel transforms in a nutshell
[N 2010] Legendre transformation and information geometry

Reading the Legendre-Fenchel transformation

- Legendre-Fenchel transformation also called the **slope transform**



$$F^*(\eta) = \sup_{\theta \in \Theta} \{\theta^\top \eta - F(\theta)\}$$



$$\begin{aligned} F(\theta) &= \exp(\theta) \\ \eta &= F'(\theta) = \exp(\theta) \\ \theta &= F'^{-1}(\eta) = \log \eta = F'^*(\eta) \\ F^*(\eta) &= \theta \eta - F(\theta) = \eta \log \eta - \eta \end{aligned}$$

(Here, F was chosen as the cumulant function of the Poisson distributions)

Legendre-Fenchel transform: Mixed coordinates and Fenchel-Young divergence

- **Dual parameterizations** of epigraph: $\theta = \nabla F^*(\eta)$ and $\eta = \nabla F(\theta)$
- Convex conjugate expressed as : $F^*(\eta) = \eta^\top \nabla F^*(\eta) - F(\nabla F^*(\eta))$
- To get in closed form the convex conjugate F^* , we need $\nabla F^*(\eta)$, i.e., invert $\nabla F(\theta)$

- **Fenchel-Young inequality:** $F(\theta_1) + F^*(\eta_2) \geq \theta_1^\top \eta_2$
with equality if and only if $\eta_2 = \nabla F(\theta_1)$
- **Fenchel-Young divergence** use mixed parameterization θ/η :
$$Y_{F,F^*}(\theta_1 : \eta_2) := F(\theta_1) + F^*(\eta_2) - \theta_1^\top \eta_2 = Y_{F^*,F}(\eta_2, \theta_1)$$

Dual Bregman and dual Fenchel divergences

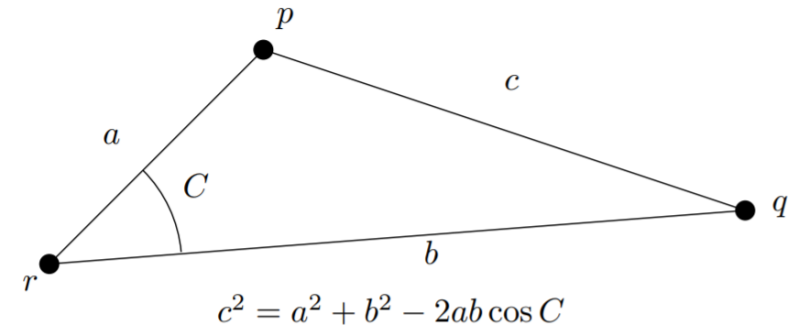
- **Identity of dual Bregman divergences:** $B_F(\theta_1 : \theta_2) = B_{F^*}(\eta_2 : \eta_1)$
- In general, dual or **reverse divergence:** $D^*(\theta_1 : \theta_2) := D(\theta_2 : \theta_1)$
- Primal, dual or mixed parameterizations of Bregman divergences:

$$B_F(\theta_1 : \theta_2) = Y_{F,F^*}(\theta_1 : \eta_2) = Y_{F^*,F}(\eta_2, \theta_1) = B_{F^*}(\eta_2 : \eta_1)$$

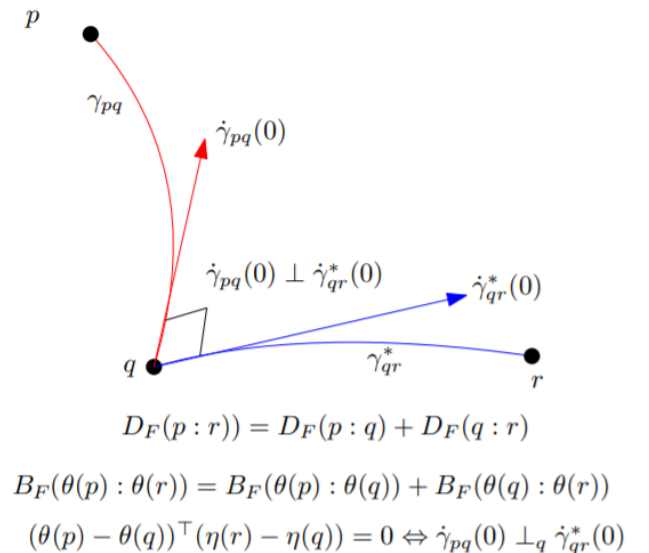
3-parameter identity of Bregman divergences

- Generalize the **law of cosines** for the squared Euclidean distance

$$B_F(\theta_1 : \theta_2) = B_F(\theta_1 : \theta_3) + B_F(\theta_3 : \theta_2) - (\theta_1 - \theta_3)^\top (\nabla F(\theta_2) - \nabla F(\theta_3)) \geq 0$$



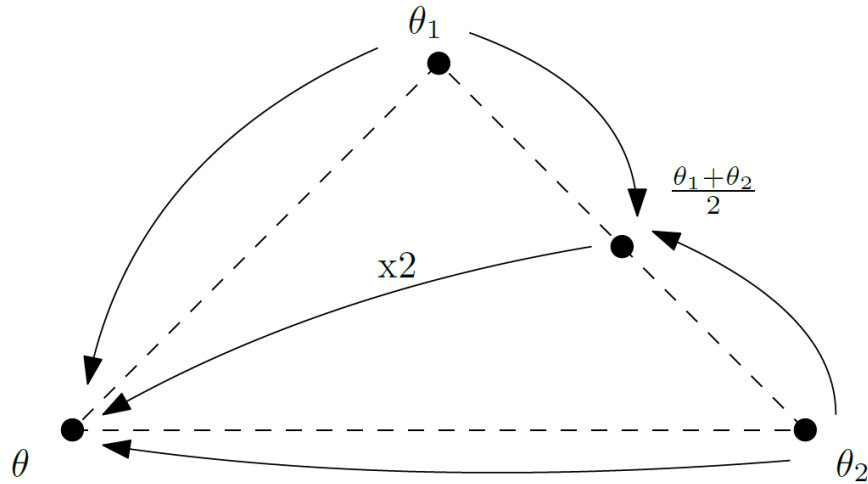
- Yields a **generalization of the Pythagorean theorem** when $(\theta_1 - \theta_3)^\top (\nabla F(\theta_2) - \nabla F(\theta_3)) = 0$



4-parameter identity of Bregman divergences

- Parallelogram identity

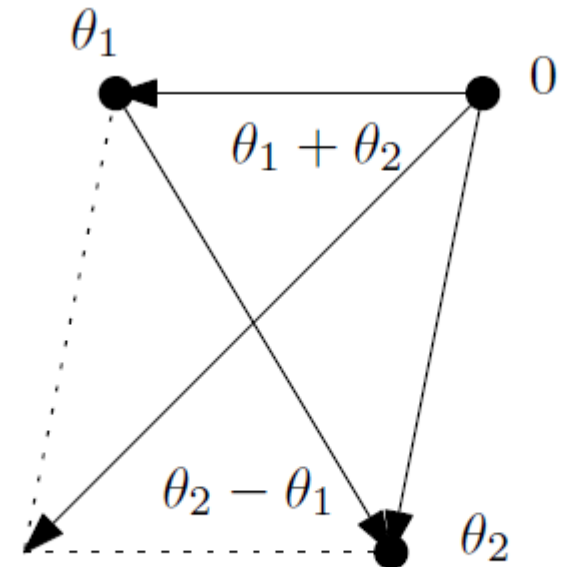
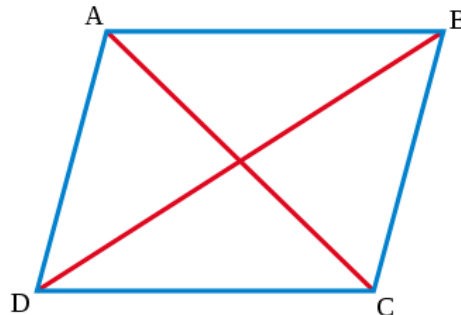
$$B_F(\theta_1 : \theta) + B_F(\theta_2 : \theta) = B_F\left(\theta_1 : \frac{\theta_1 + \theta_2}{2}\right) + B_F\left(\theta_2 : \frac{\theta_1 + \theta_2}{2}\right) + 2B_F\left(\frac{\theta_1 + \theta_2}{2} : \theta\right)$$



$$B_F(\theta_1 : \theta) + B_F(\theta_2 : \theta) = B_F\left(\theta_1 : \frac{\theta_1 + \theta_2}{2}\right) + B_F\left(\theta_2 : \frac{\theta_1 + \theta_2}{2}\right) + 2B_F\left(\frac{\theta_1 + \theta_2}{2} : \theta\right)$$

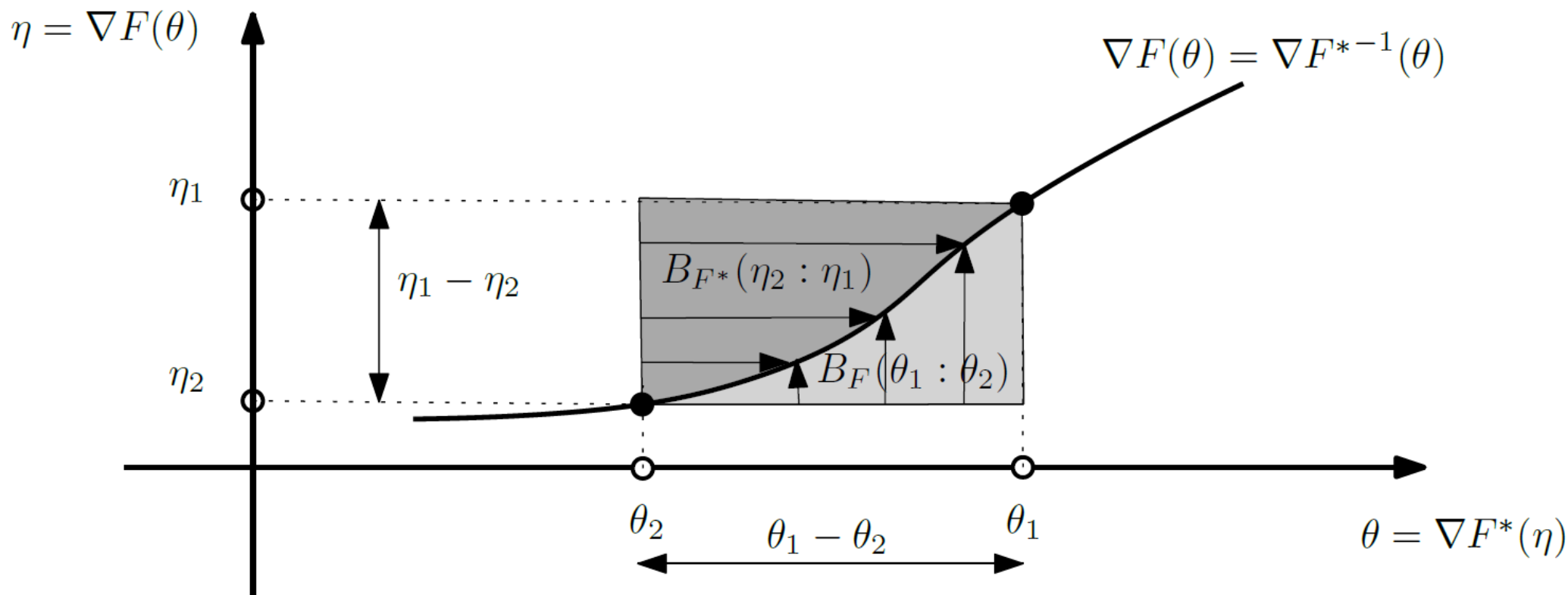
- In Euclidean geometry:

$$2AB^2 + 2BC^2 = AC^2 + BD^2$$



$$2\|\theta_1\|^2 + 2\|\theta_2\|^2 = \|\theta_1 - \theta_2\|^2 + \|\theta_1 + \theta_2\|^2$$

Symmetrized Bregman divergence: Geometric reading



$$\begin{aligned}
 B_F(\theta_1 : \theta_2) &= \int_{\theta_2}^{\theta_1} (F'(\theta) - F'(\theta_2)) d\theta & S_F(\theta_1, \theta_2) &= B_F(\theta_1 : \theta_2) + B_F(\theta_2 : \theta_1) \\
 & & &= B_F(\theta_1 : \theta_2) + B_{F^*}(\eta_1 : \eta_2) \\
 B_{F^*}(\eta_2 : \eta_1) &= \int_{\eta_1}^{\eta_2} (F^{*'}(\eta) - F^{*'}(\eta_1)) d\eta & &= (\theta_1 - \theta_2)^\top (\eta_1 - \eta_2)
 \end{aligned}$$

Statistical divergences between parametric models = parameter divergences

Statistical divergences between densities of a **parametric model** $\mathcal{F} = \{f_\theta(x)\}_\theta$ amount equivalently to (parameter) divergences between corresponding parameters:

$$\mathcal{D}[f_{\theta_1} : f_{\theta_2}] =: D_{\mathcal{M}}(\theta_1 : \theta_2)$$

For which statistical models and statistical divergences,
do we obtain $D_{\mathcal{M}}(\theta_1 : \theta_2)$ as a Bregman divergence?

Example 1: Natural exponential family models

- Parametric model $\mathcal{E} = \{e_\theta(x)\}_\theta$ with densities $e_\theta(x) = \exp\left(\sum_{i=1}^D t_i(x)\theta_i - F(\theta) + k(x)\right)$

- Examples of **natural exponential families**:

- Exponential distributions (continuous): p.d.f. $\lambda e^{-\lambda x} \quad x \geq 0$

- Poisson distributions (discrete): p.m.f. $\Pr(X=k) = \frac{\lambda^k e^{-\lambda}}{k!}$

- Examples of **exponential families** with density $e_\lambda(x) = \exp\left(\sum_{i=1}^D t_i(x)\theta_i(\lambda) - F(\theta) + k(x)\right)$

Gaussian distributions once reparameterized with natural parameters

$$\theta(\lambda) = \theta(\mu, \sigma^2)$$

- We have $\mathcal{D}_{\text{KL}}[e_{\theta_1} : e_{\theta_2}] = \underbrace{B_F^*(\theta_1 : \theta_2)}_{D_{\mathcal{E}}(\theta_1 : \theta_2)} = B_F(\theta_2 : \theta_1)$ with Bregman generator:

the **log-normalizer convex real-analytic function**: $F_{\mathcal{E}}(\theta) = \log\left(\int \exp\left(\sum_{i=1}^D t_i(x)\theta_i + k(x)\right) d\mu(x)\right)$

Example 2: Mixture family models

- Let $1, p_0(x), \dots, p_D(x)$ be $(D+2)$ **linearly independent** densities

- **Mixture family** $\mathcal{M} = \{m_\theta(x)\}_\theta$ with densities:
$$m_\theta(x) = \sum_{i=1}^D w_i p_i(x) + \left(1 - \sum_{i=1}^D w_i\right) p_0(x)$$

- We have:
$$\mathcal{D}_{\text{KL}}[m_{\theta_1} : m_{\theta_2}] = \underbrace{B_{F_{\mathcal{M}}}(\theta_1 : \theta_2)}_{D_{\mathcal{M}}(\theta_1 : \theta_2)} \quad \theta = (w_1, \dots, w_D)$$

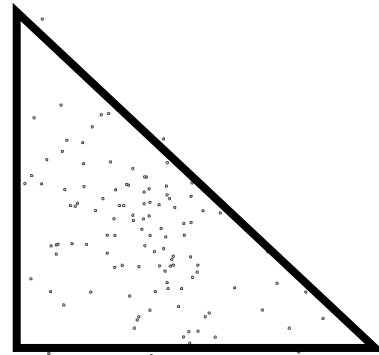
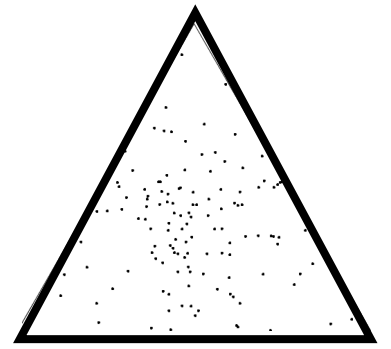
← Information geometry/reconstruction

- with the Bregman generator = **Shannon negentropy**:

$$F_{\mathcal{M}}(\theta) = \int m_\theta(x) \log m_\theta(x) d\mu(x)$$

Usually $F_{\mathcal{M}}(\theta)$ not in closed-form...

But 2-mixture family of Cauchy distributions has closed-form!



Natural parameters

Example 3: q-Gaussians and statistical divergence

- The set of **Cauchy distributions** $\mathcal{C} := \left\{ p_\lambda(x) := \frac{s}{\pi(s^2 + (x-l)^2)}, \lambda := (l, s) \in \mathbb{H} := \mathbb{R} \times \mathbb{R}_+ \right\}$ form a **q-Gaussian exponential family** for $q=2$
- Deformed exponential family generalize exponential family with deformed log/exp functions
- Cumulant function of the Cauchy 2-Gaussian family:
$$F(\theta) = -\frac{\pi^2}{\theta_2} - \frac{\theta_1^2}{4\theta_2} - 1.$$
$$(\theta_1, \theta_2) = \left(2\pi \frac{l}{s}, -\frac{\pi}{s} \right)$$
- The following statistical divergence between 2 Cauchy distributions amount to a Bregman divergence:

$$D_{\text{flat}}[p_{\lambda_1} : p_{\lambda_2}] := \frac{1}{\int p_{\lambda_2}^2(x) dx} \left(\int \frac{p_{\lambda_2}^2(x)}{p_{\lambda_1}(x)} dx - 1 \right) = \underline{B_F(\theta_1 : \theta_2)}$$

- Bregman generator is the **q-free energy** for $q=2$

Information geometry & Bregman divergences

- Bregman divergences are **canonical divergences** of dually flat spaces (Bregman manifolds)
- Information geometry gives a principle to **reconstruct** the statistical divergence corresponding to a Bregman divergence for a Bregman generator $F(f_\theta)$, and not the converse

Bregman generator

Bregman divergence

Statistical divergence

$$F_{\mathcal{E}}(\theta) = \log \left(\int \exp\left(\sum_{i=1}^D t_i(x)\theta_i + k(x)\right) d\mu(x) \right) \longrightarrow B_F(\theta_1 : \theta_2) \longrightarrow \mathcal{D}_{\text{KL}}^*[p_1 : p_2] = \mathcal{D}_{\text{KL}}[p_2 : p_1] \longrightarrow$$
$$B_F(\theta_1 : \theta_2) = \mathcal{D}_{\text{KL}}^*[e_{\theta_1} : e_{\theta_2}] = \mathcal{D}_{\text{KL}}[e_{\theta_2} : e_{\theta_1}]$$

Class of Bregman generators modulo affine terms

& KLD between exponential family densities expressed as log-ratio

- Bregman generators are strictly convex and differentiable convex functions defined modulo affine terms: $\mathbf{B}_F = \mathbf{B}_G$ iff. $F(\theta) = G(\theta) + \mathbf{A}\theta + \mathbf{b}$

- Choose for **any** ω in the support of the exponential family the Bregman generator:

$$F_\omega(\theta) := \underline{-\log(p_\theta(\omega))} = F(\theta) - \underbrace{(\theta^\top t(\omega) + k(\omega))}_{\text{affine term in } \theta}$$

- We get: $D_{\text{KL}}[p_{\lambda_1} : p_{\lambda_2}] = \log \left(\frac{p_{\lambda_1}(\omega)}{p_{\lambda_2}(\omega)} \right) + (\theta(\lambda_2) - \theta(\lambda_1))^\top (t(\omega) - \nabla F(\theta(\lambda_1)))$, $\forall \omega \in \mathcal{X}$

- By choosing s points: $D_{\text{KL}}[p_{\lambda_1} : p_{\lambda_2}] = \frac{1}{s} \sum_{i=1}^s \log \left(\frac{p_{\lambda_1}(\omega_i)}{p_{\lambda_2}(\omega_i)} \right)$ such that $\frac{1}{s} \sum_{i=1}^s t(\omega_i) = E_{p_{\lambda_1}}[t(x)]$

Computing Statistical Divergences with Sigma Points. GSI 2021

Cumulant-free closed-form formulas for some common (dis)similarities between densities of an exponential family,

arXiv:2003.02469

Part II.

Information geometry & Bregman manifolds



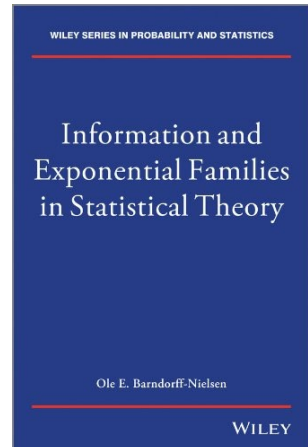
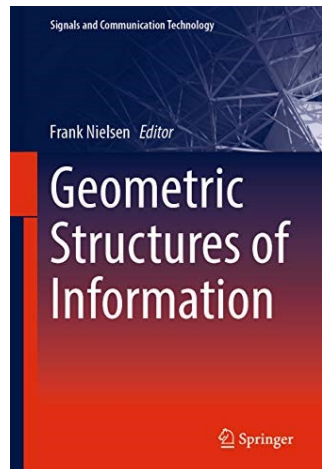
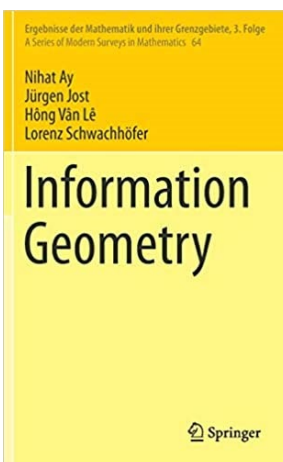
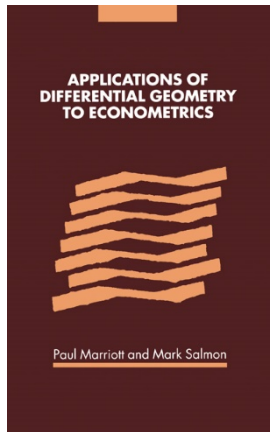
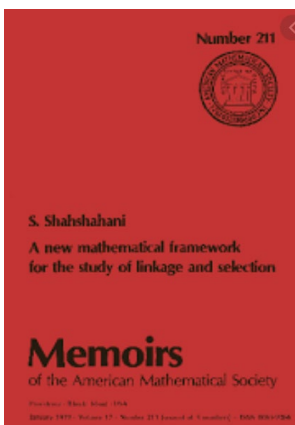
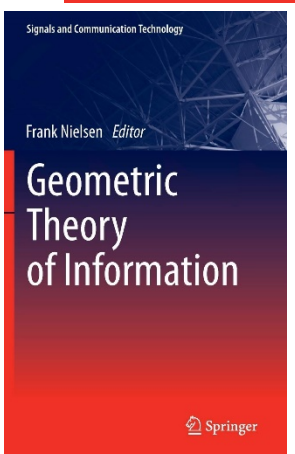
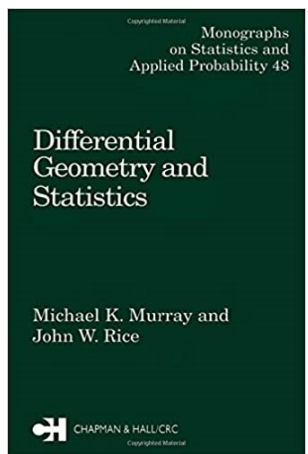
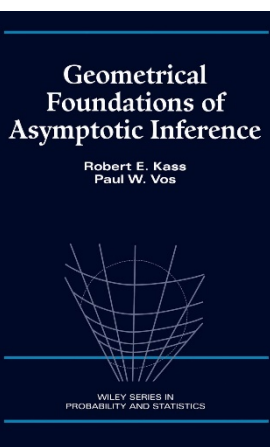
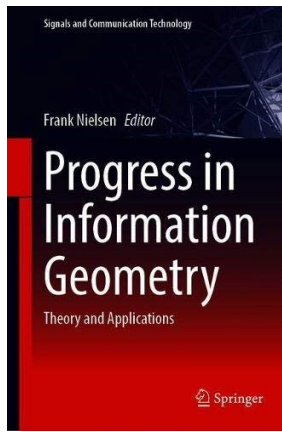
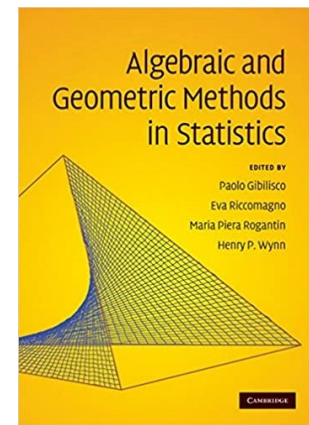
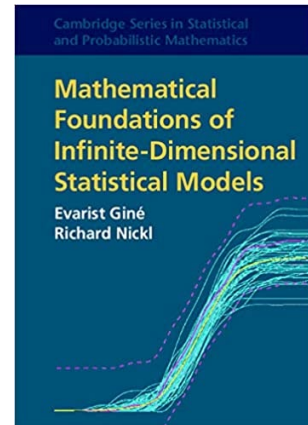
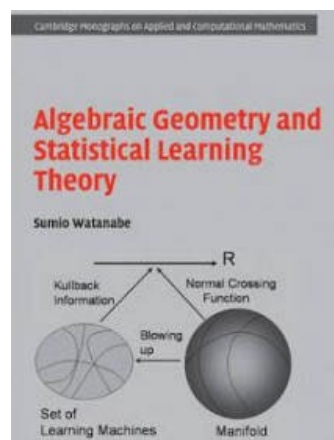
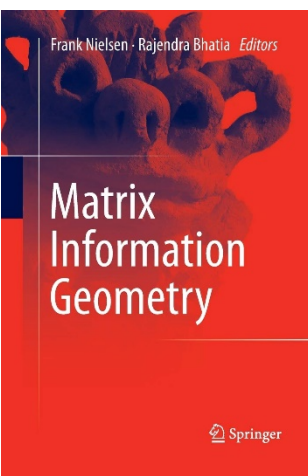
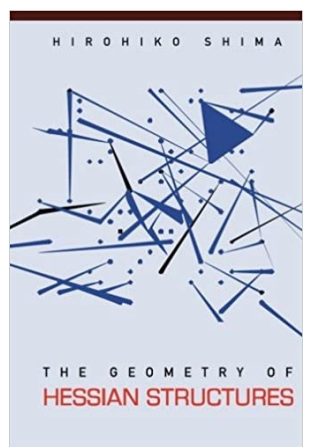
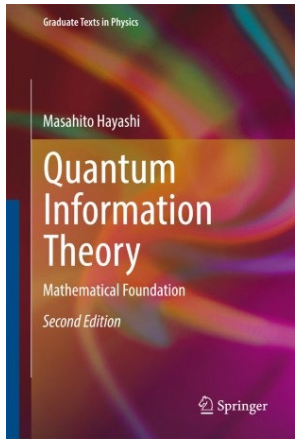
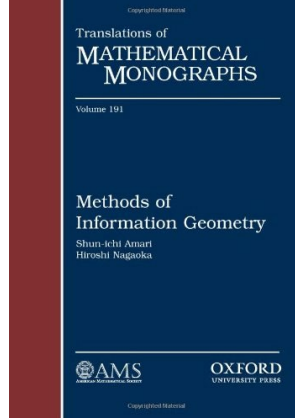
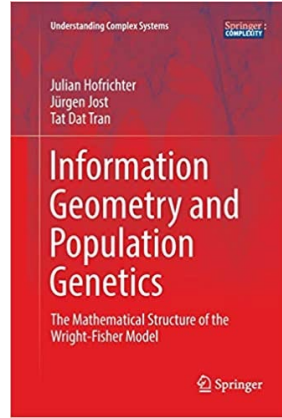
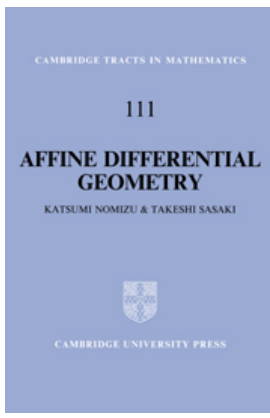
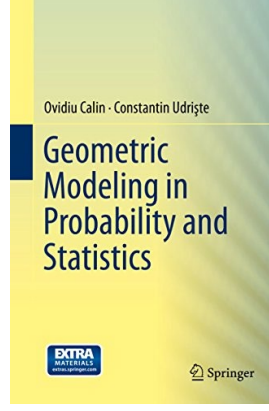
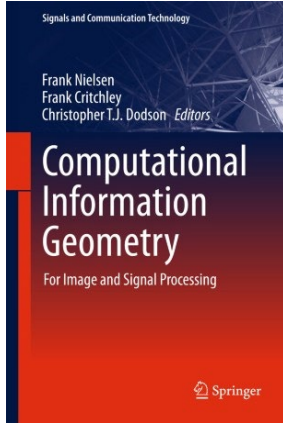
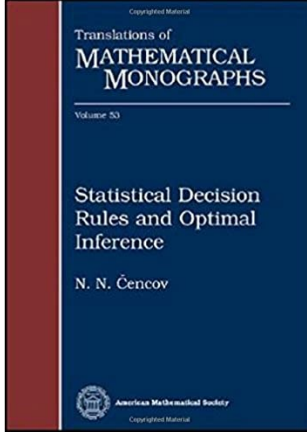
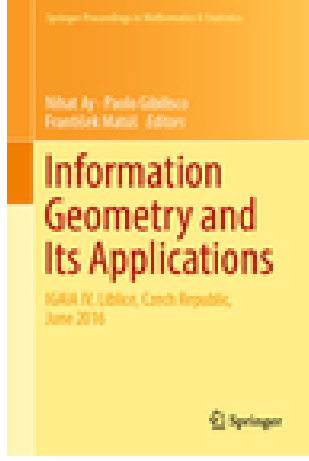
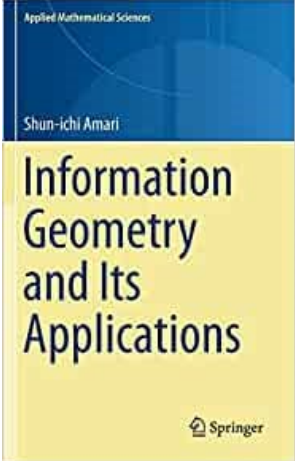
The **fabric** of information geometry
and the **untangling** of its **geometry**, **divergence**, **statistical models**

Motivation & history of information geometry

- **Information geometry** studies the geometric structures and statistical invariance principles (*sufficient statistics, Markov kernels*) of a family of probability distributions (=statistical model) and demonstrate their use in information sciences (statistics, ML).
- The newly revealed geometric structures (e.g., dually flat space) can *also* be used in **non-statistical contexts** (e.g., mathematical programming)



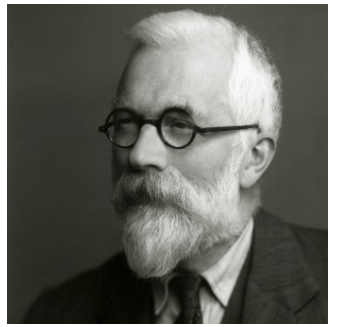
- Born as a mathematical curiosity! Use **Fisher information matrix** as a Riemannian metric = Fisher metric [Hotelling 1930] [Rao 1945]
- Decouple metric tensor with Levi-Civita connection, consider a family of affine connections [Chentsov 1960-1970's] : **Geometrostatistics**
- **Statistical curvature**, Efron's **e-connection**, Dawid's **m-connection** [Efron 1975]
- Consider **dual torsion-free affine connections coupled to the metric**, explicit **α -structures** [Amari 1980's] (Amari-Chentsov totally symmetric cubic tensor)
- Non-parametric information geometry [Pistone 1990's], quantum information geometry, algebraic statistics, geometric science of information, etc.



Part II.A

- Fisher-Riemannian geometry

Fisher information matrix (FIM)



- A parametric family of distributions $\mathcal{P} = \{p_\theta\}_{\theta \in \Theta}$
- **Fisher information matrix** is positive-semidefinite matrix:

$$\text{Score: } s(\theta) := \nabla_\theta \log p_\theta(x) \quad I_X(\theta) = \text{Cov}(s_\theta) \quad X = (x_1, \dots, x_D)^\top \sim p_\theta$$

- Under **independence**, Fisher information is **additive**:

$$Y = (Y_1, \dots, Y_n)_{\sim \text{iid} p_\theta} \Rightarrow I_Y(\theta) = n I_X(\theta)$$

- Under *regularity conditions I (FIM type 1)*: $I_1(\theta) = E_{p_\theta} [(\nabla_\theta \log p_\theta)(\nabla_\theta \log p_\theta)^\top]$
- Under *regularity conditions II (FIM type 2)*: $I_2(\theta) = -E_{p_\theta} [\nabla_\theta^2 \log p_\theta]$
- FIM can be **singular** (hierarchical models like mixtures, neural networks in ML)
- FIM can be **infinite** (irregular models, e.g., support depend on parameters)

N., Cramér-Rao lower bound and information geometry, Connected at Infinity II, 2013
Soen and Sun, On the Variance of the Fisher Information for Deep Learning, NeurIPS 2021

Key concept: Sufficient statistics

- A **statistic** is a function of a random vector (e.g., mean, variance)
- A **sufficient statistic** collect and concentrate from a random sample all necessary information for estimating the parameters.

Informally, a statistical lossless compression scheme...

- **Definition:** conditional distribution of X given t *does not depend* on θ

$$\Pr(x|\theta) = \Pr(x|t)$$

- **Fisher-Neyman factorization theorem:** Statistic $t(x)$ sufficient iff. the density can be decomposed as:

$$p(x; \lambda) = a(x)b_{\lambda}(t(x))$$

Natural exponential families (NEF)

- Consider a positive measure μ (usually counting or Lebesgue)
- A **natural exponential family** is a parametric family of densities that write as

$$p(x; \theta) = \exp(\theta x - F(\theta))$$

where F is real-analytic, strictly convex and differentiable:

$$F(\theta) = \log \int \exp(\theta x) d\mu(x)$$

Natural parameter space $\Theta = \left\{ \theta : \int \exp(\theta x) d\mu(x) < \infty \right\}$

F : **Log-normalizer** (also known as partition function, cumulant function, etc.)

Barndorff-Nielsen, Information and exponential families: in statistical theory. John Wiley & Sons, 2014

Sundberg, Statistical modelling by exponential families. Vol. 12. Cambridge University Press, 2019

N., Garcia, Statistical exponential families: A digest with flash cards." arXiv:0911.4863

Exponential families (from Natural EFs to EFs)

- Consider a **(sufficient) statistic** $t(x)$
- Consider an **additional carrier measure term** $k(x)$
- Consider an **inner product** between $t(x)$ and θ
(usual scalar/dot product)

$$p_{\theta}(x) = \exp(\langle \theta, t(x) \rangle - F(\theta) + k(x))$$

Properties:

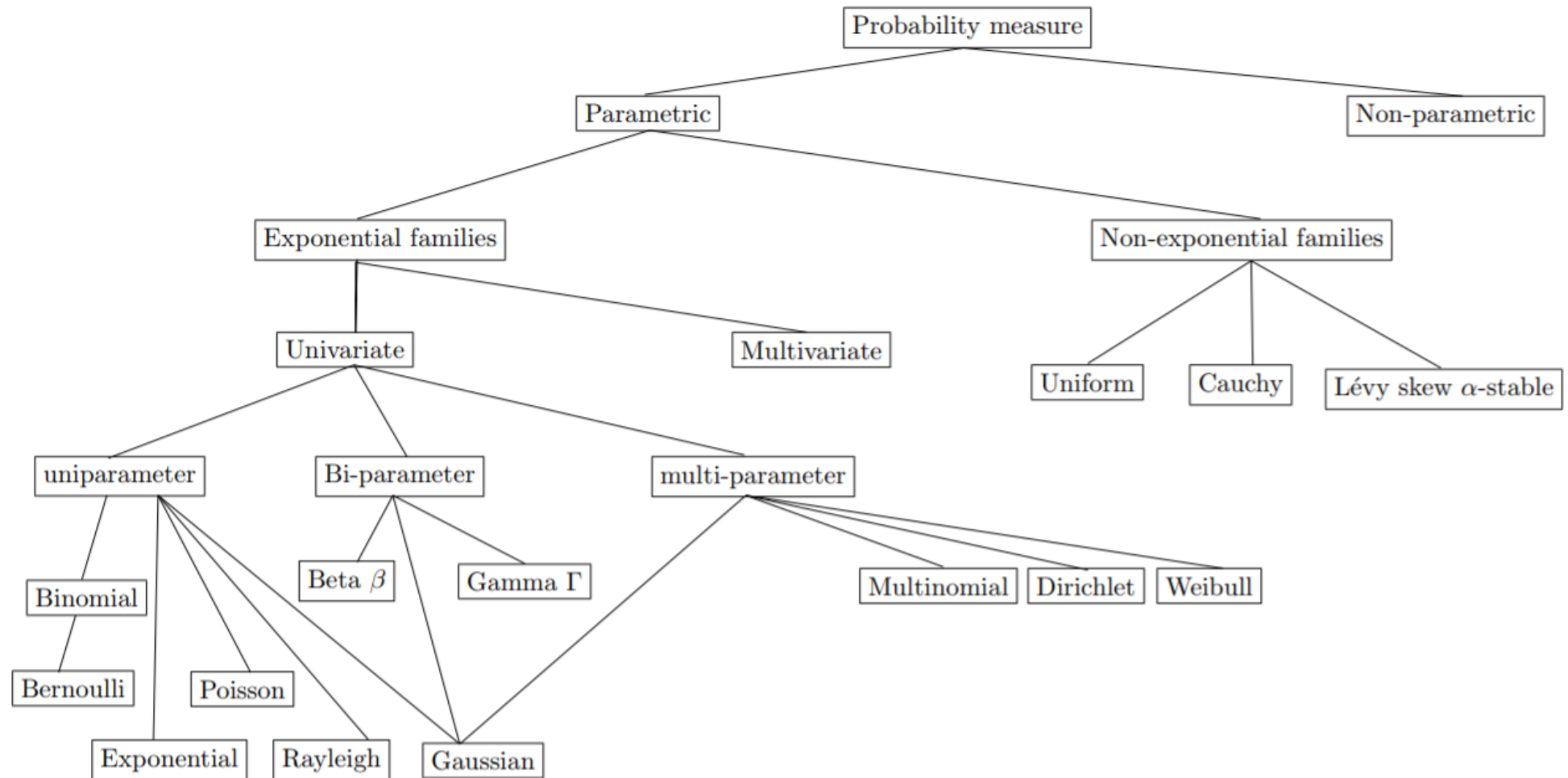
$$E[t(X)] = \nabla F(\theta)$$

$$\text{Cov}[t(X)] = \nabla^2 F(\theta) = I(\theta)$$

(Hessian of $-\log p_{\theta}(x)$)
(FIM type 2)

Exponential families have finite moments of any order

Many common distributions are exponential families in disguise



Statistical exponential families: A digest with flash cards, arXiv:0911.4863 (2009)

Tojo and Yoshino, On a method to construct exponential families by representation theory, GSI 2019 (Springer)

Bhattacharyya arc: Likelihood Ratio Exponential Family

- **Bhattacharyya arc** or **Hellinger arc** induced by two mutually absolutely continuous distributions p and q (same support \mathcal{X}):

$$\mathcal{E}(p, q) := \left\{ p_\lambda(x) := \frac{p^{1-\lambda}(x)q^\lambda(x)}{Z_\lambda^G(p, q)}, \quad \lambda \in (0, 1) \right\} \quad Z_\lambda^G(p, q) := \int_{\mathcal{X}} p^{1-\lambda}(x)q^\lambda(x)d\mu(x)$$

- Log-normalizer $F(\lambda)$ (aka cumulant generating function, log partition function):
- Bhattacharyya arc (geometric mixtures) = **1D exponential family**:

$$\begin{aligned} p_\lambda(x) &= \frac{p_0^{1-\lambda}(x)p_1^\lambda(x)}{Z_\lambda^G(p, q)} \\ &= p_0(x) \exp\left(\lambda \log\left(\frac{p_1(x)}{p_0(x)}\right) - \log Z_\lambda^G(p, q)\right) \\ &= \exp(\lambda t(x) - F(\lambda) + k(x)) \end{aligned}$$

$$\begin{aligned} F(\lambda) &:= \log(Z_\lambda^G(p, q)) = \log\left(\int_{\mathcal{X}} p^{1-\lambda}(x)q^\lambda(x)d\mu(x)\right) \\ &=: -D_\lambda^{\text{Bhat}}[p : q] \end{aligned}$$

Log-likelihood sufficient statistics:

$$t(x) := \log\left(\frac{p_1(x)}{p_0(x)}\right)$$

Base measure is p_0 $k(x) := \log p_0(x)$

$$D_\alpha^{\text{Bhat}}[p : q] := -\log\left(\int_{\mathcal{X}} p^{1-\alpha}(x)q^\alpha(x)d\mu(x)\right)$$

Rao's length distance (Riemannian distance)

(M,g) Riemannian manifold: Parameter space equipped with the **Fisher information metric**

$$d(\theta^1, \theta^2) = \min_{\theta(t)} \int_{t_1}^{t_2} \sqrt{\sum_{i=1}^p \sum_{j=1}^p g_{ij}(\theta(t)) \frac{d\theta_i(t)}{dt} \frac{d\theta_j(t)}{dt}} dt.$$

Invariant under smooth & bijective reparameterization

E.g., normal family: (μ, σ) , (μ, σ^2) , $(\mu, \log \sigma)$

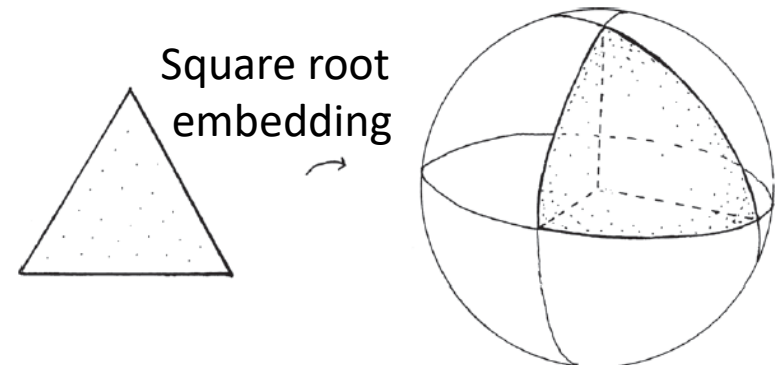
FIM is **covariant** under reparameterization



C. R. Rao with
Sir R. Fisher in 1956

Rao distance in the probability simplex:

$$\rho_{\text{FHR}}(p, q) = 2 \arccos \left(\sum_{i=0}^d \sqrt{\lambda_p^i \lambda_q^i} \right)$$



Rao's distance between 1D normal distributions

Fisher information metric becomes the Poincare upper plane metric after scale change of variable

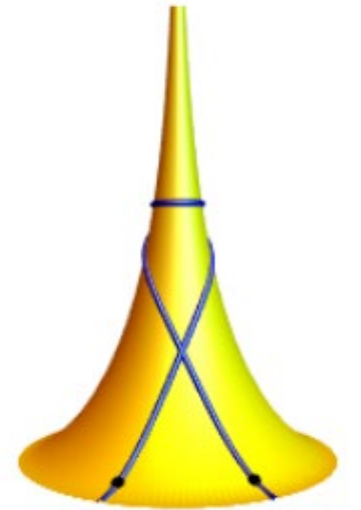
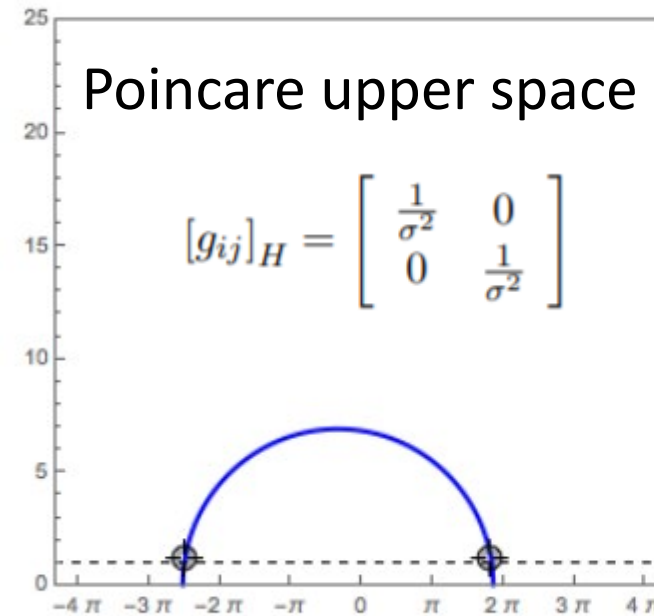
FIM of normals

$$[g_{ij}(\mu, \sigma)]_F = \begin{bmatrix} \frac{1}{\sigma^2} & 0 \\ 0 & \frac{2}{\sigma^2} \end{bmatrix}$$

$$ds_F^2 = \frac{d\mu^2 + 2d\sigma^2}{\sigma^2}.$$

$$d_F((\mu_1, \sigma_1), (\mu_2, \sigma_2)) = \sqrt{2}d_H \left(\left(\frac{\mu_1}{\sqrt{2}}, \sigma_1 \right), \left(\frac{\mu_2}{\sqrt{2}}, \sigma_2 \right) \right)$$

$$\text{dist}(\langle x_1, y_1 \rangle, \langle x_2, y_2 \rangle) = \text{arcosh} \left(1 + \frac{(x_2 - x_1)^2 + (y_2 - y_1)^2}{2y_1 y_2} \right)$$



Pseudo-sphere
partial embedding
in \mathbb{R}^3

In practice, calculating Rao's distance may be difficult!

E.g., no closed form
of Rao's distance
between multivariate normals

$$d(\boldsymbol{\theta}^1, \boldsymbol{\theta}^2) = \min_{\boldsymbol{\theta}(t)} \int_{t_1}^{t_2} \sqrt{\sum_{i=1}^p \sum_{j=1}^p g_{ij}(\boldsymbol{\theta}(t)) \frac{d\theta_i(t)}{dt} \frac{d\theta_j(t)}{dt}} dt.$$

1. Need to solve the Ordinary Differential Equation (ODE) to find the **geodesic**:

$$\frac{d^2\theta_k}{dt^2} + \sum_{i=1}^p \sum_{j=1}^p \Gamma_{ij}^k \frac{d\theta_i}{dt} \frac{d\theta_j}{dt} = 0, \quad k = 1, \dots, p,$$

$$\Gamma_{ij}^k = \frac{1}{2} \sum_{m=1}^p \left(\frac{\partial g_{im}(\boldsymbol{\theta})}{\partial \theta_j} + \frac{\partial g_{jm}(\boldsymbol{\theta})}{\partial \theta_i} - \frac{\partial g_{ij}(\boldsymbol{\theta})}{\partial \theta_m} \right) g^{mk}(\boldsymbol{\theta}), \quad i, j, k = 1, \dots, p,$$

2. Need to **integrate** the infinitesimal length elements ds along the geodesics

Approximating geodesics for MVNs: geodesic shooting

Algorithm 1 Shooting method for minimal geodesics on $\mathcal{N}(n)$

Given: Initial point $P_0 = (\mu_0, \Sigma_0)$, final point $P_1 = (\mu_1, \Sigma_1)$.

Output: Minimal geodesic $P(t) = (\mu(t), \Sigma(t))$, $t \in [0, 1]$, such that $P(1) = (\mu_1, \Sigma_1)$.

Initialization: Choose initial velocities $V(0) = (\dot{\mu}(0), \dot{\Sigma}(0))$ (e.g., zeroes), initial values for ϵ (10^{-5}), error = 10^6 .

while error $\geq \epsilon$ **do**

 Numerically integrate the geodesic equations (13), (14) for given initial conditions $(\mu_0, \Sigma_0, \dot{\mu}_0, \dot{\Sigma}_0)$ from $t = 0$ to $t = 1$

 Denote the solution by $(\mu(t), \Sigma(t))$;

 Set $W(1) = (W_\mu(1), W_\Sigma(1)) = (\mu_1 - \mu(1), \Sigma_1 - \Sigma(1))$;

 Calculate error = $\|W(1)\|_{P_1} = \sqrt{W_\mu(1)^T \Sigma_1^{-1} W_\mu(1) + \frac{1}{2} \text{tr}((\Sigma_1^{-1} W_\Sigma(1))^2)}$;

 Numerically integrate the parallel transport equations (18) and (19) for given trajectory $(\mu(t), \Sigma(t))$ and final velocities $W(1)$, backward in time from $t = 1$ to $t = 0$;

 Numerically calculate Jacobi field $J(1)$ from (22),

$J(1) = \frac{\exp_{P_0}(V(0) + \alpha W(0)) - \exp_{P_0}(V(0))}{\alpha}$, where α is sufficiently small value and we use $\frac{\epsilon}{\|W(0)\|_{P_0}}$

 Determine proper update size s :

$$s_1 = \frac{\langle W(1), J(1) \rangle_{P(1)}}{\|J(1)\|_{P(1)}^2}$$

if $\|W(1)\|_{P(1)} > 0.05$ **then**

$$s = 0.05 / \|W(1)\|_{P(1)} s_1;$$

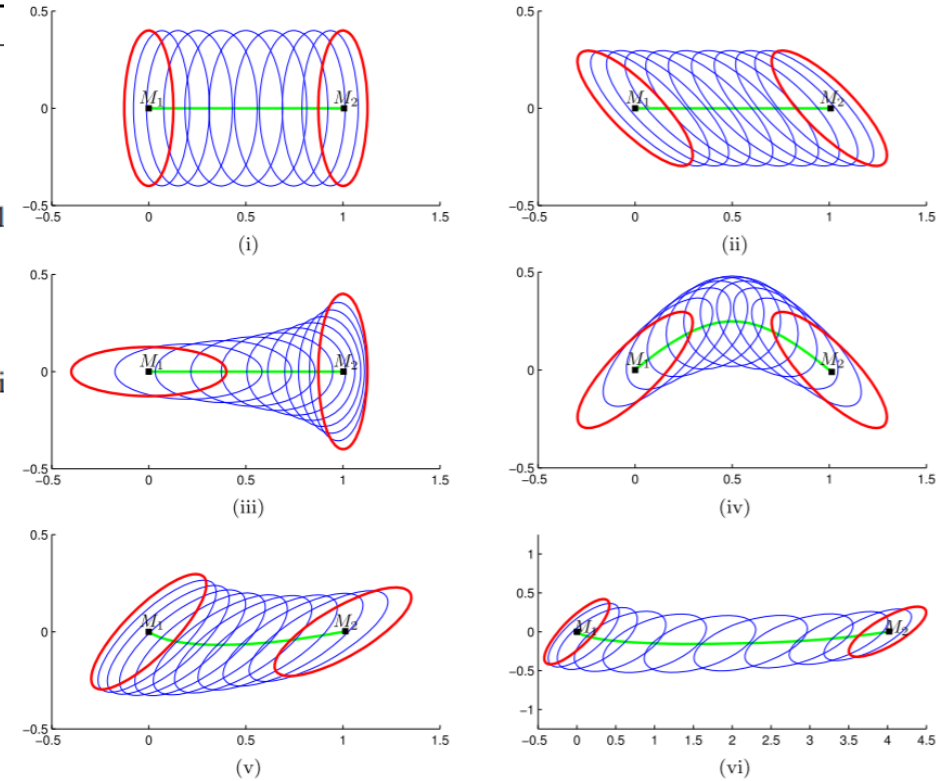
else

$$s = s_1;$$

end if

$$V(0) \leftarrow V(0) + sW(0);$$

end while



ODE with boundary value conditions

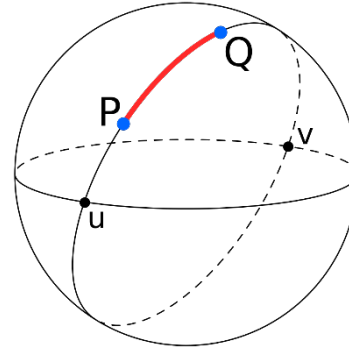
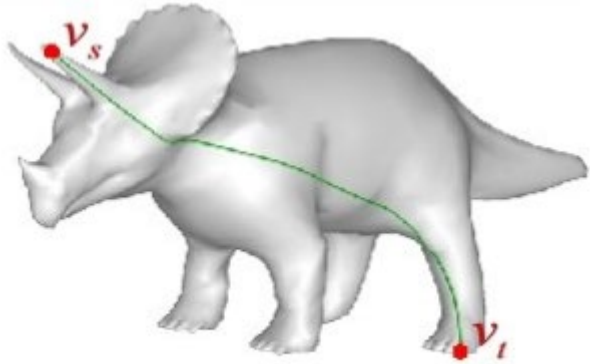
Minyeon Han · F.C. Park, DTI Segmentation and Fiber Tracking Using Metrics on Multivariate Normal Distributions, 2014
 Calvo, Miquel, and Josep Maria Oller. "An explicit solution of information geodesic equations for the multivariate normal model." *Statistics & Risk Modeling* 9.1-2 (1991): 119-138.

Part II.B

- Dual information geometry

Another look at Riemannian geodesics: Connections

- Riemannian geodesics are **locally minimizing length curves**



- The *general definition* of geodesics is wrt. to an **affine connection**:
For Riemannian geodesics, the default connection = **Levi-Civita connection**.

This special Levi-Civita connection is derived from the metric tensor g .

- A geodesic $\gamma(t)$ with respect to a connection ∇ is an **∇ -autoparallel curve** (straight free fall particle in physics):

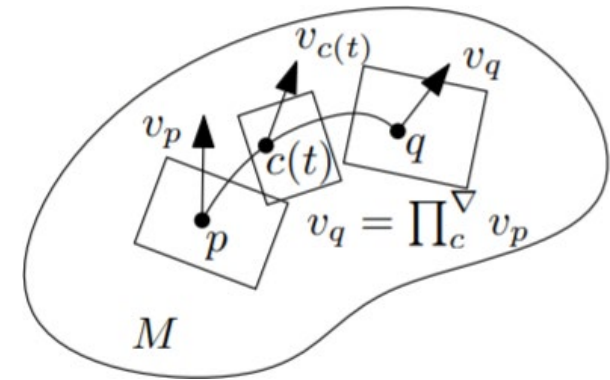
$$\nabla_{\dot{\gamma}} \dot{\gamma} = 0, \quad \dot{\gamma} = \frac{d}{dt} \gamma(t)$$

where $\nabla_X T$ is the **covariant derivative** of a tensor T wrt. a vector field X

What makes the Levi-Civita connection so special?

- A connection is described by **Christoffel symbols** (functions Γ), and the geodesics is described by this ODE: $\ddot{\gamma}(t) + \Gamma_{ij}^k \dot{\gamma}(t) \dot{\gamma}(t) = 0$, $\gamma^l(t) = x^l \circ \gamma(t)$,

An affine connection defines how to **parallel transport** a vector from one tangent plane to another tangent plane



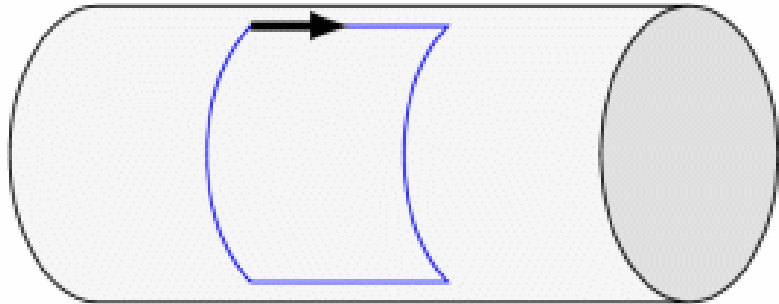
- Fundamental theorem of Riemann geometry:

Levi-Civita connection is the **unique torsion-free metric connection** induced by the metric tensor g

$${}^{\text{LC}}\Gamma_{ij}^k \stackrel{\Sigma}{=} \frac{1}{2} g^{kl} (\partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij})$$

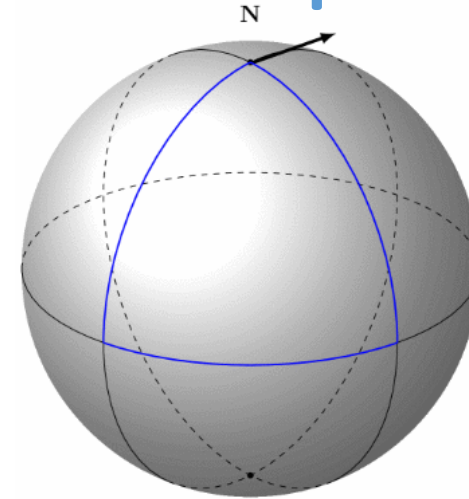
$$\langle u, v \rangle_{c(0)} = \left\langle \prod_{c(0) \rightarrow c(t)}^{\nabla} u, \prod_{c(0) \rightarrow c(t)}^{\nabla} v \right\rangle_{c(t)} \quad \forall t.$$

∇ : Curvature, torsion, and parallel transport



Cylinder is **flat**

Parallel transport is
independent of path



Sphere has constant curvature

Parallel transport is path-dependent

A connection is flat if there exists locally a coordinate system such that the Christoffel symbols are all zero: Geodesics plotted in that coordinate system are line segments

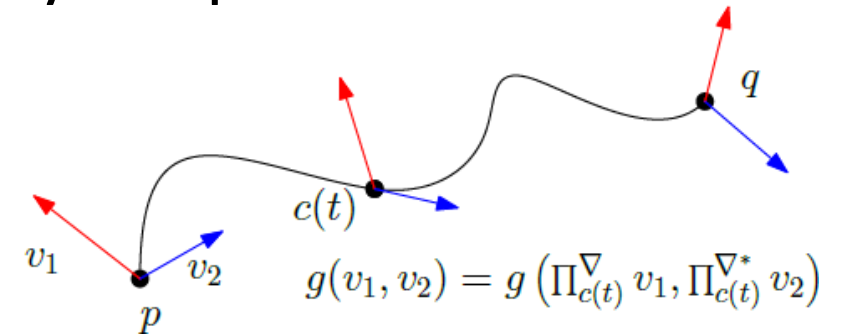
Torsion tensor $T(X, Y) := \nabla_X Y - \nabla_Y X - [X, Y]$

Connections that differ only on torsions yield same geodesics

Dualistic information geometry: (M, g, ∇, ∇^*)

- Given an affine torsion-free connection ∇ and a metric g , we can build a **unique** dual affine torsion-free connection: the **dual connection ∇^*** such that the metric (inner product) is preserved by the primal and dual parallel transports:

$$\langle u, v \rangle_{c(0)} = \left\langle \prod_{c(0) \rightarrow c(t)}^{\nabla} u, \prod_{c(0) \rightarrow c(t)}^{\nabla^*} v \right\rangle_{c(t)}.$$



- This amounts to say that ∇^* is defined uniquely by

$$Xg(Y, Z) = g(\nabla_X Y, Z) + g(Y, \nabla_X^* Z),$$

meaning $X_p g_p(Y_p, Z_p) = g_p((\nabla_X Y)_p, Z_p) + g_p(Y_p, (\nabla_X^* Z)_p)$.

- The dual of a dual connection is the primal connection: $(\nabla^*)^* = \nabla$.

Amari/Chentsov's α -structures

$$\left\{ (\mathcal{P}, \mathcal{P}g, \mathcal{P}\nabla^{-\alpha}, \mathcal{P}\nabla^{+\alpha}) \right\}_{\alpha \in \mathbb{R}}$$

- Regular statistical parametric models (identifiable and finite positive-definite FIM) $\mathcal{P} := \{p_\theta(x)\}_{\theta \in \Theta}$

- Amari's **α -connections**

$${}_{\mathcal{P}}\Gamma^{\alpha}_{ij,k}(\theta) := E_{\theta} \left[\left(\partial_i \partial_{j,l} + \frac{1-\alpha}{2} \partial_{i,l} \partial_{j,l} \right) (\partial_{k,l}) \right].$$

$$l(\theta; x) := \log L(\theta; x) = \log p_\theta(x)$$

- 0-connection is **Fisher Levi-Civita connection**
- 1-connection is **exponential connection** (flat for exponential families)
- -1 connection is **mixture connection** (flat for mixture families)

Lauritzen' statistical manifolds: Cubic tensor

Beware: Apply also to non-statistical contexts too! (M, g, C)

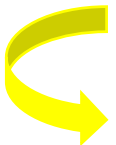
Dualistic structure with metric tensor g and **cubic tensor** C

$$C(X, Y, Z) := \langle \nabla_X Y - \nabla_X^* Y, Z \rangle \quad C = \nabla g$$

$$C_{ijk} = C(\partial_i, \partial_j, \partial_k) = \langle \nabla_{\partial_i} \partial_j - \nabla_{\partial_i}^* \partial_j, \partial_k \rangle$$

C is **totally symmetric** (= components invariant by index permutation)

In a local basis: $C_{ijk} := \Gamma_{ij}^k - \Gamma_{ij}^{*k}$


$${}^{LC}\nabla g = 0$$



Levi-Civita connection is self-dual with respect to the metric!

Eguchi's Information geometry of divergences

- **Reverse/dual parameter divergence** (reference duality)

$$D^*(\theta : \theta') := D(\theta' : \theta) \quad (D^*)^* = D$$

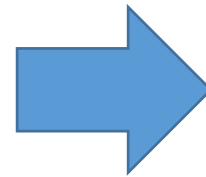
- Statistical manifold structures:

$$(M, {}^D g, {}^D \nabla, {}^{D^*} \nabla) \quad (M, {}^D g, {}^D C)$$

$${}^D g := -\partial_{i,j} D(\theta : \theta')|_{\theta=\theta'} = {}^{D^*} g,$$

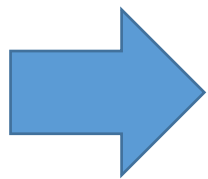
$${}^D C_{ijk} = {}^{D^*} \Gamma_{ijk} - {}^D \Gamma_{ijk}$$

$${}^D \Gamma_{ijk} := -\partial_{ij,k} D(\theta : \theta')|_{\theta=\theta'},$$



$${}^{D^*} \Gamma_{ijk} := -\partial_{k,ij} D(\theta : \theta')|_{\theta=\theta'}.$$

$${}^D \nabla^* = {}^{D^*} \nabla$$

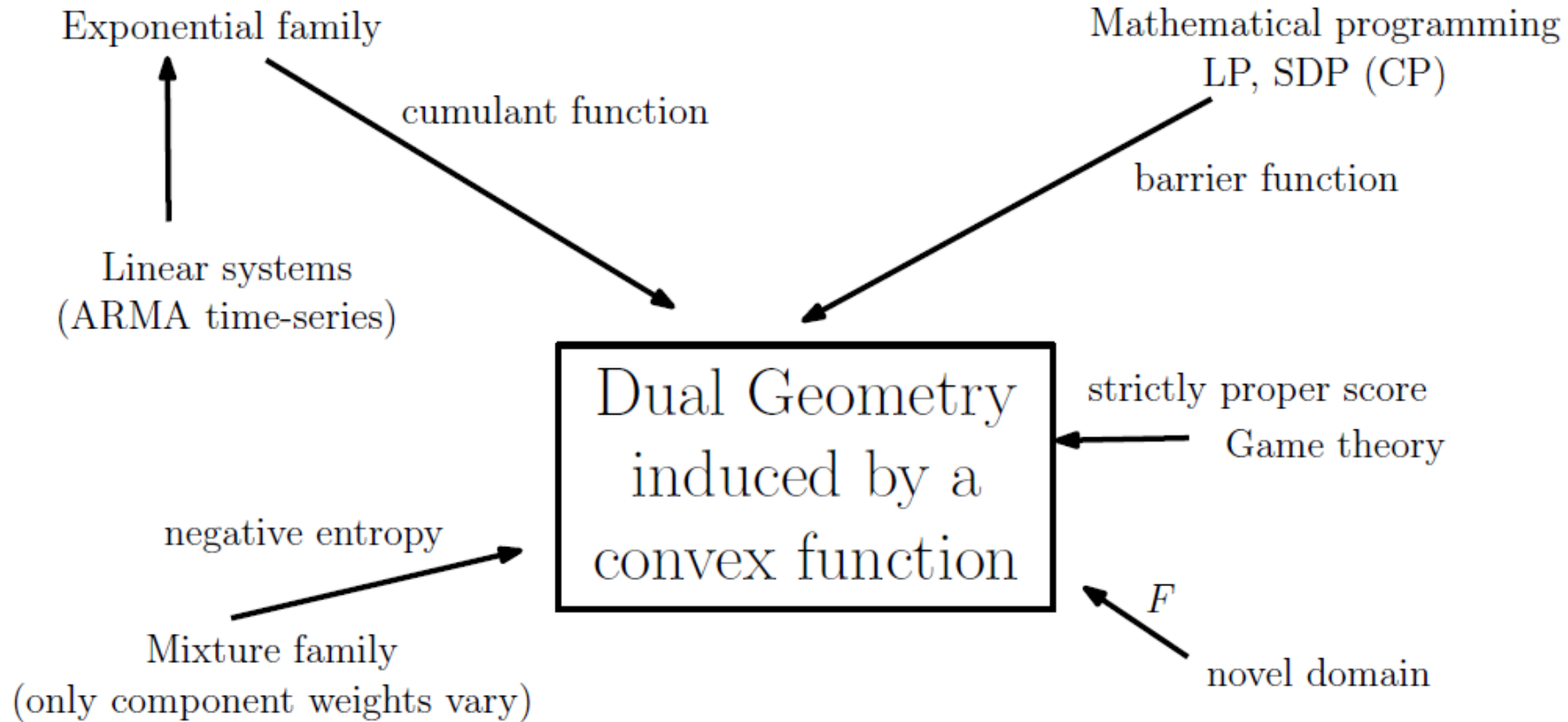


$$\left\{ (M, {}^D g, {}^D C^\alpha) \equiv (M, {}^D g, {}^D \nabla^{-\alpha}, ({}^D \nabla^{-\alpha})^* = {}^D \nabla^\alpha) \right\}_{\alpha \in \mathbb{R}}$$

Part II.C

- Bregman manifolds: Dually flat spaces

Dually flat geometry from a convex function



Not necessarily related to statistical models,
but can always be realized by a regular statistical model

Metric tensor using covariant/contravariant notations

2-covariant metric tensor in local coordinates:

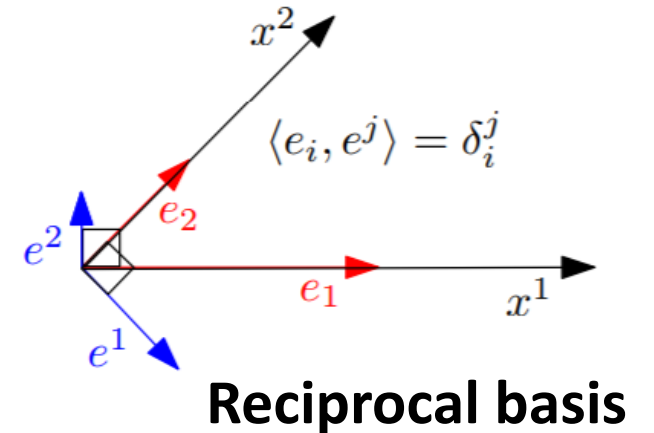
$$g_{ij}(\theta) = \nabla^2 F(\theta)$$

Dual metric tensor in local coordinates:

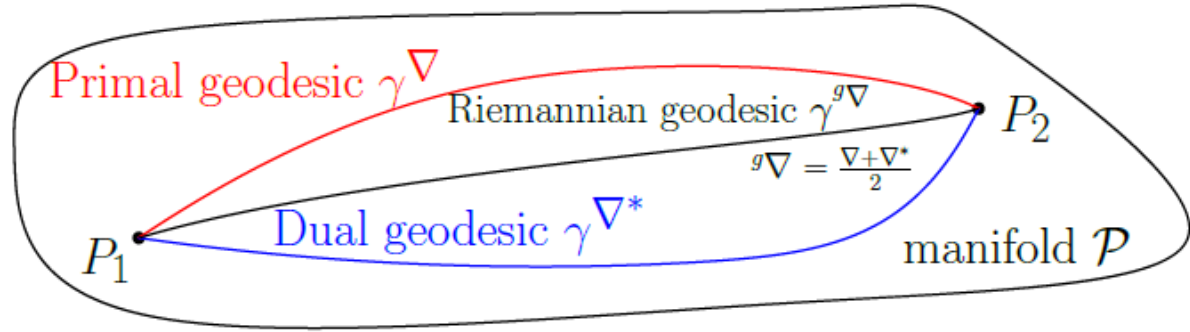
$$g^{ij}(\eta) = g^{*ij}(\eta) = \nabla^2 F^*(\eta)$$

Crouzeix's identity: x of Hessians of convex conjugates = Id:

$$\nabla^2 F(\theta) \nabla^2 F^*(\eta) = I$$



Bregman information geometry: Bregman manifolds



- Start from a potential function $F(\theta)$

$$F g = \nabla^2 F(\theta)$$

- Get the dual potential function $F^*(\eta)$

$$F g^* = \nabla^2 F^*(\eta)$$

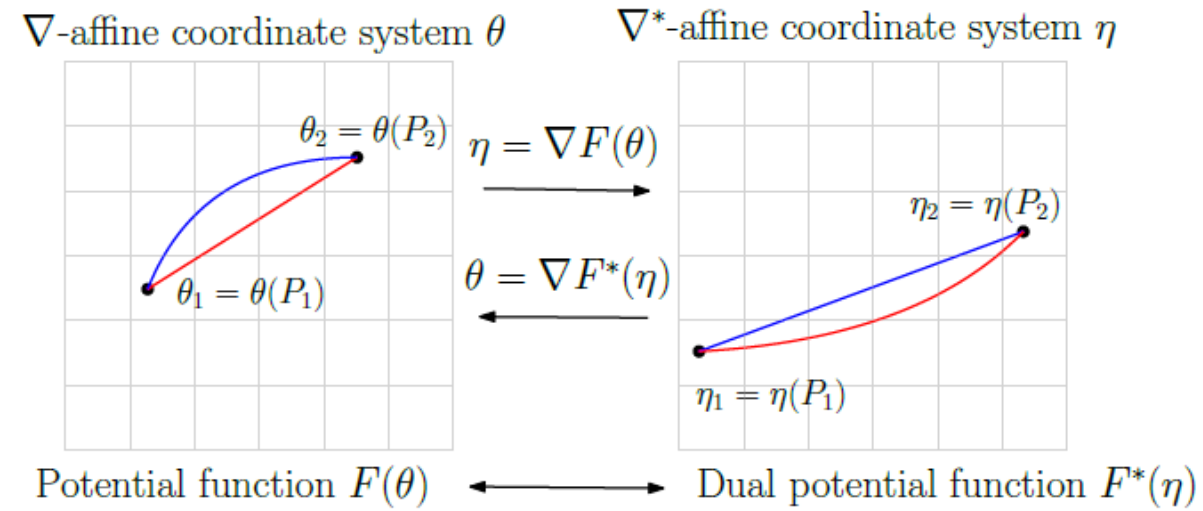
- Define the primal flat connection:

$$F \Gamma_{ijk}(\theta) = 0$$

- Define the dual flat connection:

$$F \Gamma^{*ijk}(\eta) = 0$$

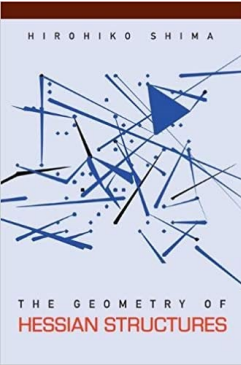
- Get the dual Bregman divergences or dual Fenchel-Young divergences



Legendre-Fenchel transform

$$F^*(\eta) = \sup_{\theta \in \Theta} \{\theta^\top \eta - F(\theta)\}$$

Bregman manifolds vs Hessian manifolds



- **Hessian metric** wrt. a **flat connection** ∇ . function is 0-form on M:

Riemannian Hessian metric when $g = \nabla^2 F_M$

- **Hessian operator:** $(\nabla^2 F_M)(X, Y) := (\nabla_X d)(F_M(Y)) = X(dF_M(Y)) - dF_M(\nabla_X Y)$

$$\nabla^2 F_M(\partial_{x^i}, \partial_{x^j}) = \frac{\partial^2 F_M}{\partial x^i \partial x^j} - \Gamma_{ij}^k \frac{\partial F_M}{\partial x^k} \quad \xrightarrow{\nabla \text{ flat}} \quad \nabla^2 F_M(\partial_{x^i}, \partial_{x^j}) = \frac{\partial^2 F_M}{\partial x^i \partial x^j}$$

- **Bregman manifold:** geometry on an open convex domain:

Here, ∇ = gradient

Here, ∇, ∇^* = affine flat connections

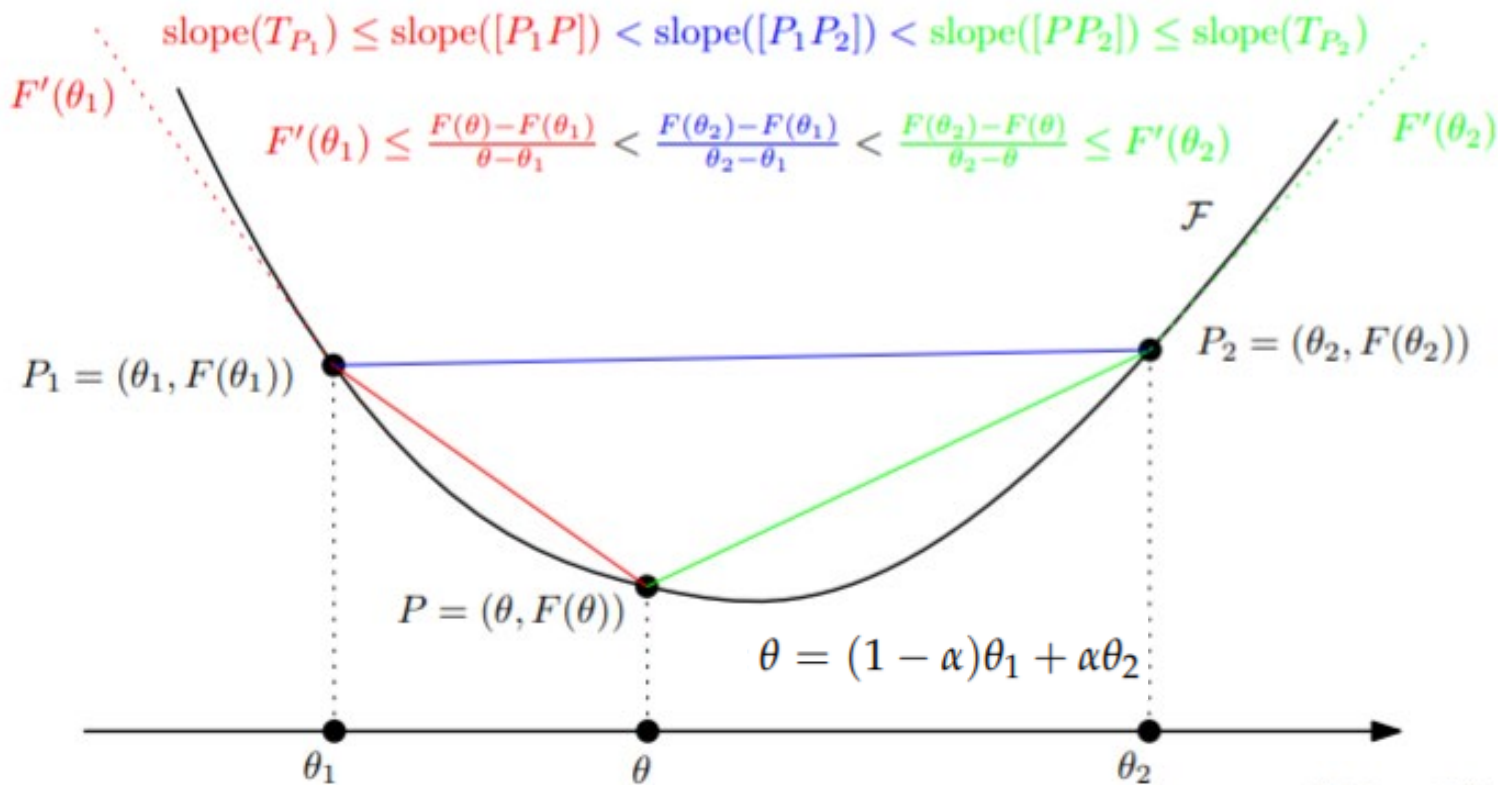
$$g(\theta) = \nabla^2 F(\theta) \quad \xrightarrow{\quad} \quad \nabla : \Gamma_{ijk}(\theta) = 0$$

$$g^*(\eta) = \nabla^2 F^*(\eta) \quad \xrightarrow{\quad} \quad \nabla^* : \Gamma^{*ijk}(\eta) = 0$$

Part III

Generalized convexity and divergences from
convexity gaps

Chordal slope lemma & Jensen/Bregman divergences



Jensen Divergence (JD)

$$\frac{F(\theta) - F(\theta_1)}{\alpha(\theta_2 - \theta_1)} < \frac{F(\theta_2) - F(\theta_1)}{(\theta_2 - \theta_1)}$$



$$F(\theta) - F(\theta_1) < \alpha(F(\theta_2) - F(\theta_1))$$



$$\alpha(F(\theta_2) - F(\theta_1)) - F(\theta) + F(\theta_1) > 0,$$



$$\underline{J_F^\alpha(\theta_1 : \theta_2) := (1 - \alpha)F(\theta_1) + \alpha F(\theta_2) - F((1 - \alpha)\theta_1 + \alpha\theta_2) > 0.}$$

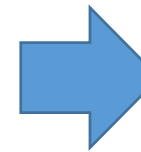
Bregman

Divergences (BDs):

$$F'(\theta_1) \leq \frac{F(\theta_2) - F(\theta_1)}{\theta_2 - \theta_1} \leq F'(\theta_2)$$



$$\begin{aligned} F(\theta_2) - F(\theta_1) - (\theta_2 - \theta_1)F'(\theta_1) &\geq 0, \\ F(\theta_2) - F(\theta_1) - (\theta_2 - \theta_1)F'(\theta_2) &\leq 0. \end{aligned}$$



$$\underline{B_F(\theta_2 : \theta_1) \geq 0,}$$

$$\underline{B_F(\theta_1 : \theta_2) \geq 0.}$$

BD as a limit of a scaled JD: $B_F(\theta_1 : \theta_2) = \lim_{\alpha \rightarrow 1^-} \frac{1}{\alpha(1 - \alpha)} J_{F,\alpha}(\theta_1 : \theta_2)$

[EIG, Entropy 2020]

Bregman divergences wrt comparative convexity

- Two **abstract means** M and N , i.e. $\min\{p, q\} \leq M(p, q) \leq \max\{p, q\}$.

- Define a function F **(M,N) convex** if

$$F(M(p, q)) \leq N(F(p), F(q)), \quad \forall p, q \in \mathcal{X},$$

- Consider the means **regular**: homogeneous, symmetric continuous, and increasing in each variable
- Define **skew (M,N)-Jensen divergence** for a strictly convex (M,N)-function for regular means M and N :

$$J_{F,\alpha}^{M,N}(p : q) = N_\alpha(F(p), F(q)) - F(M_\alpha(p, q)).$$

- By analogy of ordinary Bregman divergences obtained as limit of scaled skew Jensen divergences, define **(M,N)-Bregman divergences**:

$$B_F^{M,N}(p : q) = \lim_{\alpha \rightarrow 1^-} \frac{1}{\alpha(1-\alpha)} J_{F,\alpha}^{M,N}(p : q) = \lim_{\alpha \rightarrow 1^-} \frac{1}{\alpha(1-\alpha)} (N_\alpha(F(p), F(q)) - F(M_\alpha(p, q)))$$

Quasi-arithmetic (rho-tau)-Bregman divergences

- For a strictly continuously monotone function γ , define the

weighted quasi-arithmetic means $M_{\gamma,\alpha}(x, y) = \gamma^{-1}((1 - \alpha)\gamma(x) + \alpha\gamma(y))$

- **Quasi-arithmetic Bregman divergence:**

$$B_F^{\rho,\tau}(q : p) = \lim_{\alpha \rightarrow 0} \frac{1}{\alpha(1 - \alpha)} (M_{\tau,\alpha}(F(p), F(q))) - F(M_{\rho,\alpha}(p, q)))$$

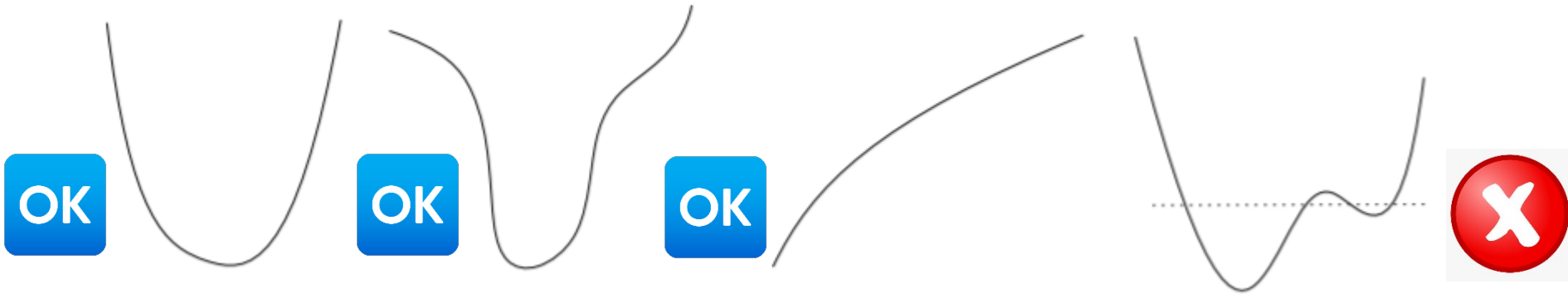
$$B_F^{\rho,\tau}(q : p) = \lim_{\alpha \rightarrow 0} \frac{1}{\alpha(1 - \alpha)} (M_{\tau,\alpha}(F(p), F(q))) - F(M_{\rho,\alpha}(p, q)))$$

- Consider the ordinary convex function: $G(x) = \tau(F(\rho^{-1}(x)))$
- Quasi-arithmetic (rho-tau)-Bregman divergences is a **conformal regular Bregman divergence:**

$$B_F^{\rho,\tau}(p : q) = \frac{1}{\tau'(F(q))} B_G(\rho(p) : \rho(q))$$

Quasi-convex Jensen and Bregman divergences

- **Strictly quasiconvex function:** $Q((\theta\theta')_\alpha) < \max\{Q(\theta), Q(\theta')\}$, $\theta \neq \theta' \in \Theta$
 $(\theta\theta')_\alpha := (1 - \alpha)\theta + \alpha\theta'$



- **Quasiconvex Jensen divergence:**

$$\begin{aligned} \text{qcvx } J_Q^\alpha(\theta : \theta') &:= \max\{Q(\theta), Q(\theta')\} - Q((\theta\theta')_\alpha) \geq 0, \\ &= \max\{Q(\theta), Q(\theta')\} - Q((1 - \alpha)\theta + \alpha\theta'). \end{aligned}$$

- Quasiconvex Jensen divergence is a **(Max,A)-Jensen divergence!**

Multivariate Bregman divergence as a family of univariate Bregman divergences

Proposition *A multivariate Bregman divergence $B_F(\theta_1 : \theta_2)$ can be written equivalently as a univariate Bregman divergence $B_{F_{\theta_1, \theta_2}}(0 : 1)$:*

$$\forall \theta_1, \theta_2 \in \Theta, \quad B_F(\theta_1 : \theta_2) = B_{F_{\theta_1, \theta_2}}(0 : 1),$$

1D Bregman generator

where

$$F_{\theta_1, \theta_2}(u) := F(\theta_1 + u(\theta_2 - \theta_1))$$

is a univariate Bregman divergence.

Proof: The univariate functions F_{θ_1, θ_2} are proper 1D Bregman generators:

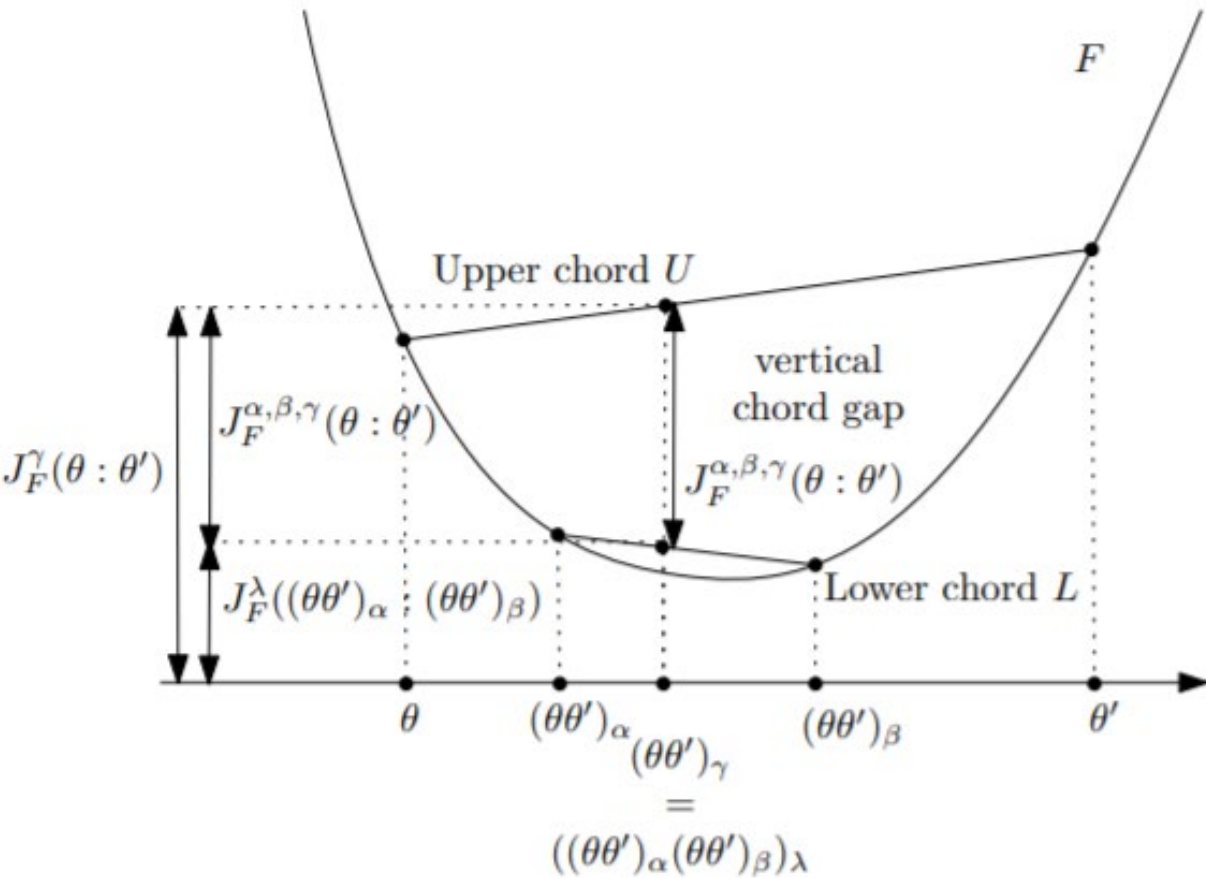
We have the directional derivative:

$$\begin{aligned} \nabla_{\theta_2 - \theta_1} F_{\theta_1, \theta_2}(u) &= \lim_{\epsilon \rightarrow 0} \frac{F(\theta_1 + (\epsilon + u)(\theta_2 - \theta_1)) - F(\theta_1 + u(\theta_2 - \theta_1))}{\epsilon}, \\ &= (\theta_2 - \theta_1)^\top \nabla F(\theta_1 + u(\theta_2 - \theta_1)), \end{aligned}$$

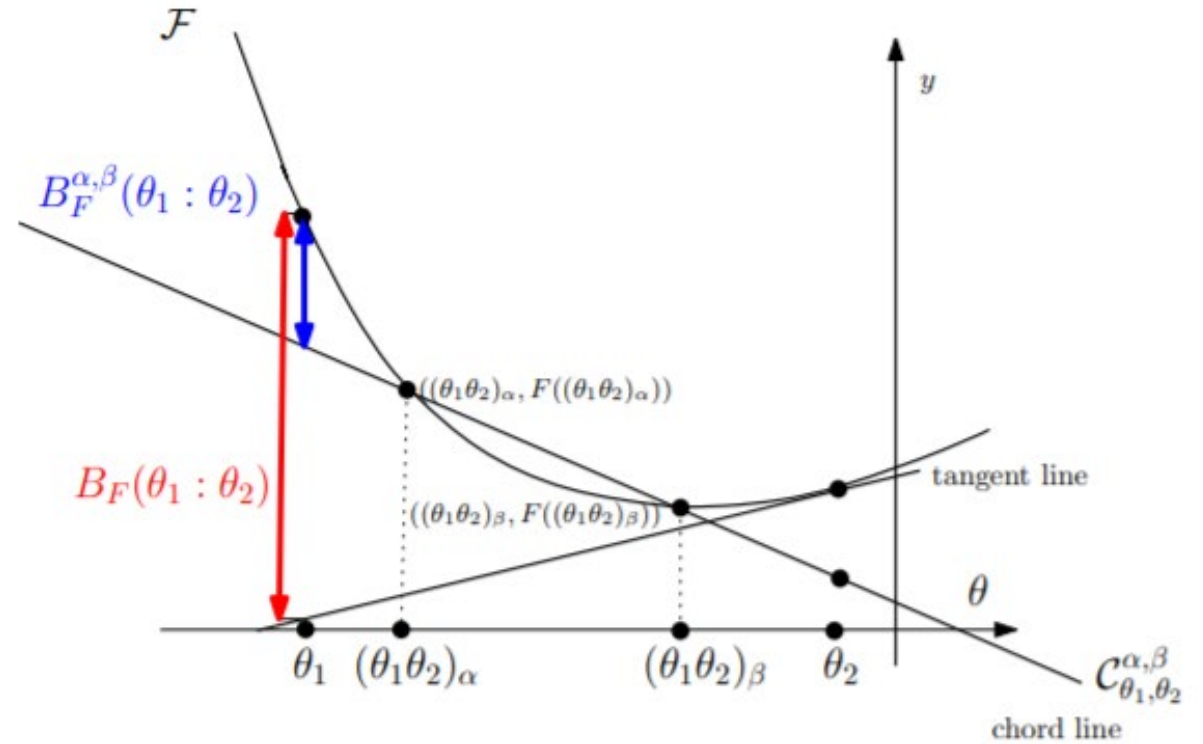
Since $F_{\theta_1, \theta_2}(0) = F(\theta_1)$, $F_{\theta_1, \theta_2}(1) = F(\theta_2)$, and $F'_{\theta_1, \theta_2}(u) = \nabla_{\theta_2 - \theta_1} F_{\theta_1, \theta_2}(u)$, it follows that

$$\begin{aligned} B_{F_{\theta_1, \theta_2}}(0 : 1) &= F_{\theta_1, \theta_2}(0) - F_{\theta_1, \theta_2}(1) - (0 - 1) \nabla_{\theta_2 - \theta_1} F_{\theta_1, \theta_2}(1), \\ &= F(\theta_1) - F(\theta_2) + (\theta_2 - \theta_1)^\top \nabla F(\theta_2) = B_F(\theta_1 : \theta_2). \end{aligned}$$

Designing divergences by measuring convexity gaps



$$J_F^{\alpha, \beta, \gamma}(\theta : \theta') := (F(\theta)F(\theta'))_\gamma - (F((\theta\theta')_\alpha)F((\theta\theta')_\beta))_{\frac{\gamma-\alpha}{\beta-\alpha}},$$



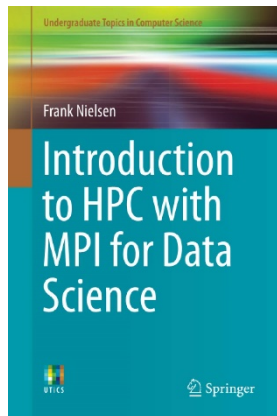
$$\begin{aligned} B_F^{\alpha, \beta}(\theta_1 : \theta_2) &:= F(\theta_1) - F((\theta_1\theta_2)_\alpha) - (\theta_1 - (\theta_1\theta_2)_\alpha)^\top \nabla F((\theta_1\theta_2)_\alpha), \\ &= F(\theta_1) - F((\theta_1\theta_2)_\alpha) - \alpha(\theta_1 - \theta_2)^\top \nabla F((\theta_1\theta_2)_\alpha), \end{aligned}$$

Thank you!

“The only constant in life is change” -Heraclitus

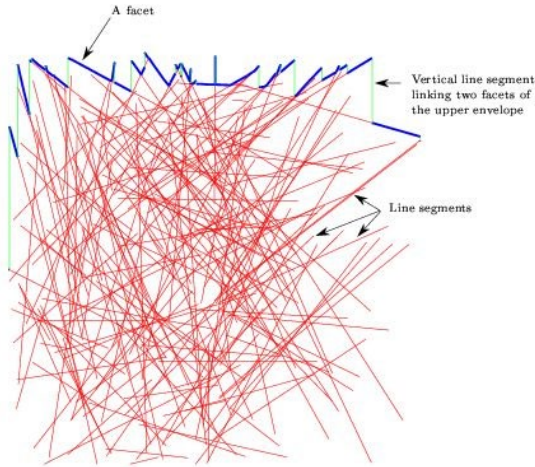
My motto: "Invariance is the only constant in change!"

<https://franknielsen.github.io/>

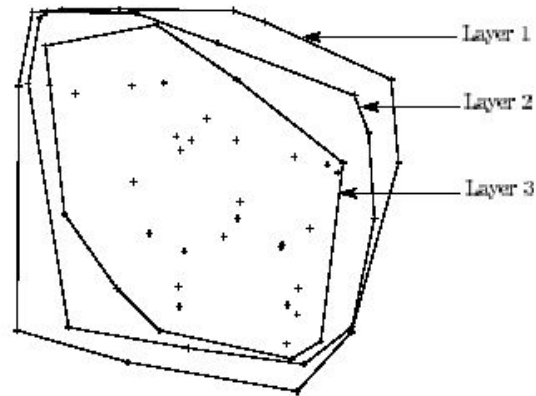


Adaptive computational geometry (PhD, 1996)

Computational geometry: Output-sensitive algorithms

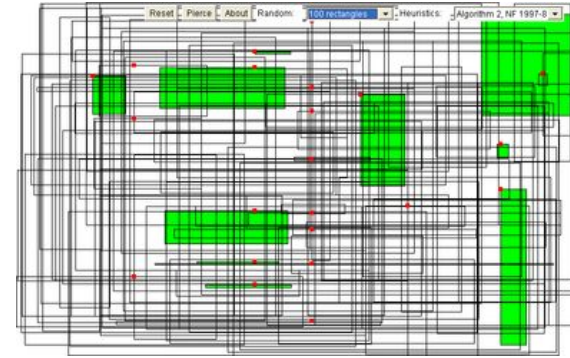


**Output-sensitive
2D lower envelopes
convex hull of objects**



**Output-sensitive peeling
of k convex or maximal layers
(Pareto front)**

Combinatorial geometry: Piercing/covering:



**Piercing/stabbing
d-dimensional isothetic boxes
Klee's measure problem**

Objects	k	Time
homothetic triangles	2	$O(n)$ (Helly-type)
4, 5-oriented polygons	2	$O(n \log n)$
d -dim. c -oriented polytopes	2	$O(n^{\min\{\lfloor \frac{d}{2} \rfloor, d\}} \log n)$
$(d+1)$ -oriented simplices	2	$O(n^{\lceil \frac{d}{2} \rceil} \log n)$
d -dim. boxes	2	$O(n)$ (Helly-type)
homothetic triangles	3	$O(n \log n)$

**Convex geometry:
Helly and Hellyinger
numbers for piercing**

- Algorithmes géométriques adaptatifs (PhD), Université Nice Sophia Antipolis, 1996
- Output-sensitive peeling of convex and maximal layers, Information processing letters 59.5 (1996): 255-259.
- An output-sensitive convex hull algorithm for planar objects, Int. J. Computational Geometry & Applications, 8.01 (1998): 39-65.
- On piercing sets of objects, Proceedings of the twelfth annual symposium on Computational geometry. 1996.
- Fast stabbing of boxes in high dimensions, Theoretical Computer Science 246.1-2 (2000): 53-72.
- On point covers of c -oriented polygons, Theoretical computer science 263.1-2 (2001): 17-29.

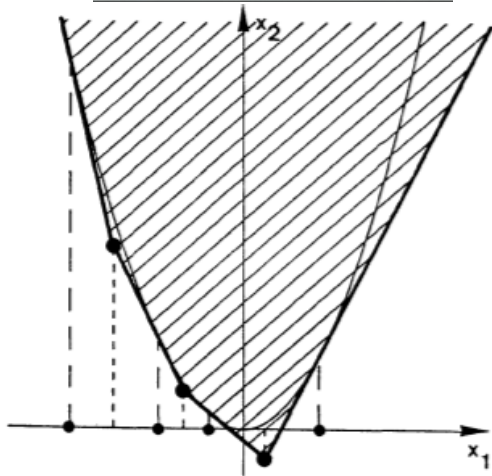
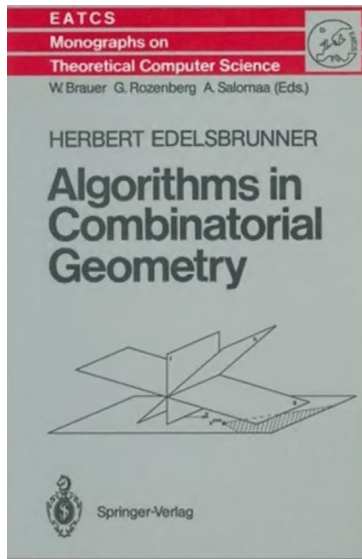
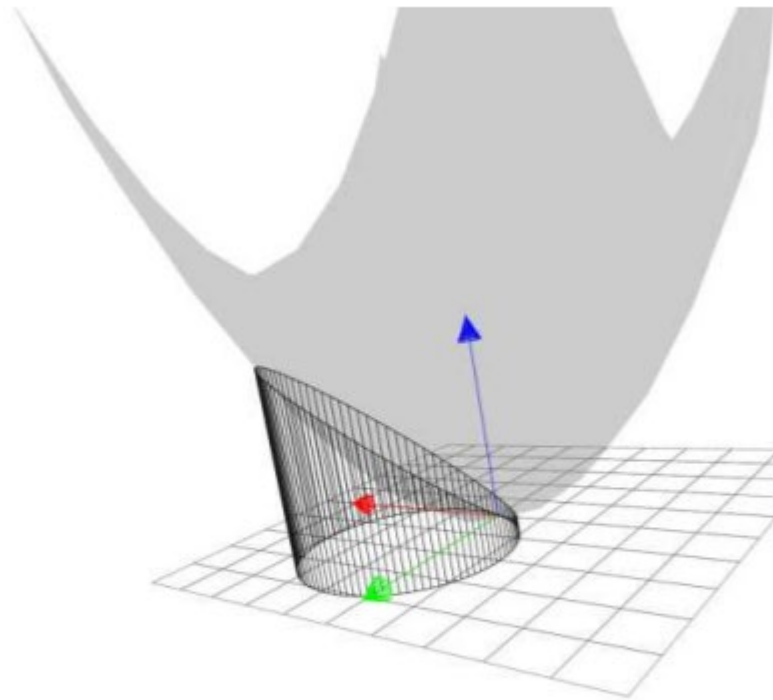
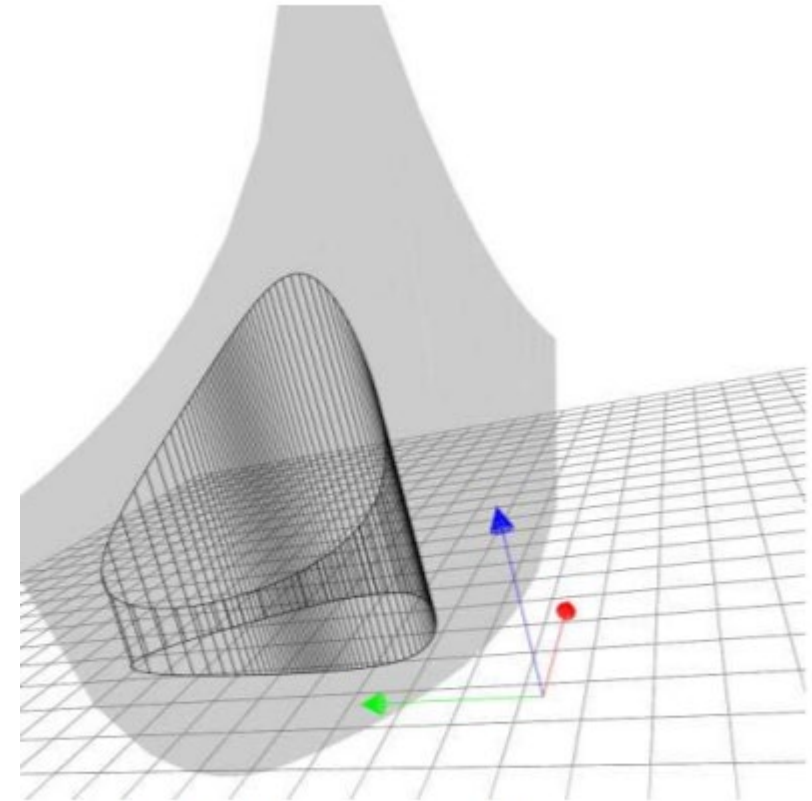


Figure 13.2. Voronoi diagram and convex polyhedron.

[Voronoi by mapping to the paraboloid]



(a) Squared Euclidean distance



(b) Itakura-Saito divergence

[Bregman Voronoi by mapping to Bregman potential functions]

The **fabric** of information geometry
and the **untangling** of its **geometry**, **divergence**, **statistical models**

divergence

statistics

models

geometry